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# AS-74.4192 Elementary Cybernetics

## Lecture 9: About “Artificial Evolution”



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- Neocybernetic visions have been tested also in practice – there are various doctoral theses being completed in 2009:
  - *Kalle Halmevaara*
    - *Optimization of large-scale plant/model parameters*
  - *Jani Kaartinen*
    - *Camera analysis in mineral processing*
  - *Olli Haavisto*
    - *Enhancing measurements using visual spectra*
  - **Neocybernetics is not explicitly mentioned in these theses!**



# Views into future

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- In process automation, we are still at the level of constructing simple controls (or *constraints*) one by one
- In the long run, however, “nothing in complex systems (now *industrial automation*) makes sense without ... evolution”
- One should understand the general process of enhancing of processes – perhaps neocybernetic intuitions can help here?
- In what follows, **examples of “artificial evolution” are studied**
- Remember the inverse view: The systems are seen from above, assuming they are internally consistent and controlled – they yield when they are pushed, and this happens in the directions of the linear *degrees of freedom*



# “Artificial cells” with “synthetic metabolism”

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- Production plants are changing into “bio-logical cells”:
  - There is intake of raw materials, production of “metabolites” (products) being as efficient as possible
  - There is a balance among economical constraints and technical possibilities, new innovations changing this balance
  - After adaptation there is better balance also in terms of tolerance against disturbances and changes in the environment
  - Evolution in the system is manifested in terms of new local controls that make the system stiffer and more robust, the system becoming “pancausal”
  - Systems are “allo cybernetic”, evolution being implemented by humans (or, engineers): whenever there is new information, there are new feedbacks
  - Local adaptations are typically implemented in terms of SISO (PID!) controls, such “atoms of enhancement” decreasing degrees of freedom by one
  - On the other hand, cybernetized systems become more and more unstable, oscillating on the edge of chaos!



# Cybernetization – systems become “stiffer”

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- Humans are the agents that implement the enhancements
- However, the dynamics are not dictated by the humans, systems having their own internal dynamics
  - The local goals are: The subsystem “tries” to become somehow *better* – faster, cheaper, more accurate, ...
  - Typically, the system goal is hypothetical, never reached – for example, zero cost, zero delay, etc.
  - The cybernetic balance is determined by technical / economical / social possibilities and constraints
  - Another factor in the dynamics is inertia among people, limiting the rate of change in the system
- This is very heuristic – is there any way of making the discussions more concrete?



# Towards “smooth evolution”

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- The evolutionary processes are often thought to be random walk processes with no continuity / differentiability properties

**Is this assumption always necessary?**

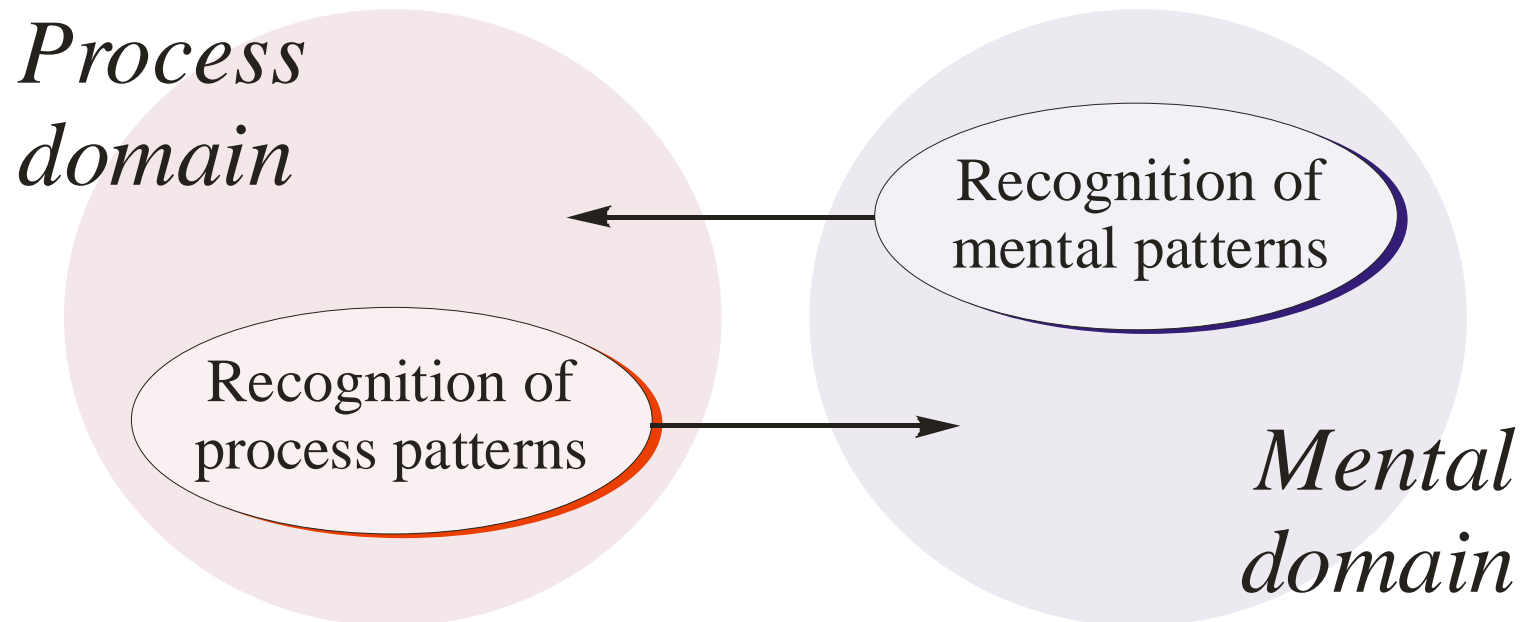
- No – the claim here is that (at least in some cases, when remaining *within one structural alternative*) the process of evolution can be continuous and differentiable
- On the higher level, system parameters are the variables of the emergent model
- There exist degrees of freedom in that parameter space with continuity of behaviors, regardless of underlying constraints
- **Smoothness is mechanism applied by natural evolution, too**



# “Second-Order Neocybernetics” simplified

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- Now it is assumed that both domains can be modeled in linear terms: just one operating regime – simple “patterns”



# Conclusion from before

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- Cybernetic models have the same structure, no matter if they are based on populations, networks, or constraints – **Linear reduced-dimension latent variable subspace, multivariate models representing dynamic equilibria**
- All systems can be studied in the same framework – applying PCA / factor analysis, etc., as seen from above
- High dimensionality, redundancies, noise, etc., are efficiently tackled with
- However, one is not interested in the “natural direction”, but one would like to affect this according to expert knowledge – do not trust input data alone (PCA style), but find a **compromise between variation in input and in output.**





# Restructuring data

- To reach practically applicable models, the homogeneous data has to be divided in input and output parameters:

**“Qualifiers”**  $\theta = \begin{pmatrix} \theta_1 \\ \vdots \\ \theta_n \end{pmatrix}$  and  $\Theta = \begin{pmatrix} \theta^T(1) \\ \vdots \\ \theta^T(k) \end{pmatrix}$  **“Process domain”**  
(inputs)  
Not only parameters but reference values, ...

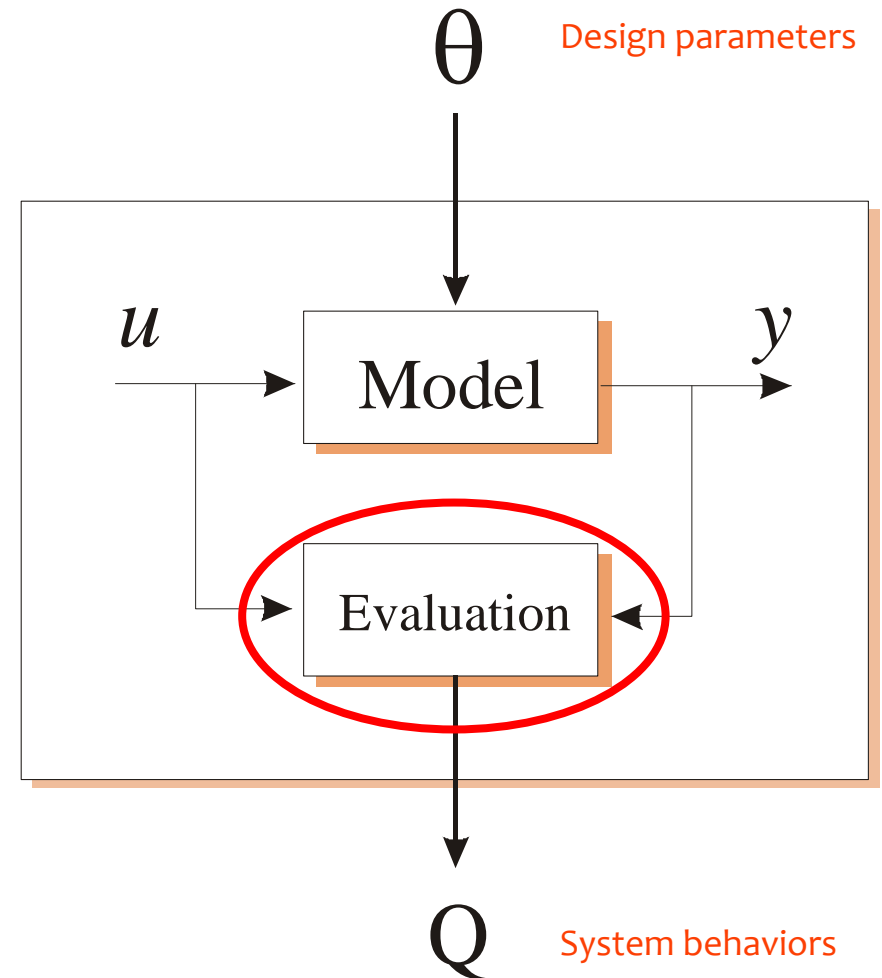
**“Qualities”**  $q = \begin{pmatrix} q_1 \\ \vdots \\ q_m \end{pmatrix}$  and  $Q = \begin{pmatrix} q^T(1) \\ \vdots \\ q^T(k) \end{pmatrix}$  **“Mental domain”**  
(outputs)  
Quality characteristics of practical interest

- Determination of the causal structure has to be carried out by a domain area expert



# From signals to “emergent-level variables”

- Higher abstraction level for looking at processes on a slower time scale
- Model from *quantifiers*  $\Theta$  to *qualities*  $Q$  rather than between signals  $u$  and  $y$
- Evaluation = link between statistics and conceptually relevant structures
- Abstraction and data compression based on behavior-based relevance



# Advantages of the approach

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- **Simplicity**

- Dynamic structures can be studied *statically*, individual signal realizations can be forgotten

- **Homogeneity**

- Model outlook remains consistent, no matter how high in the hierarchy the submodel is

- **Generality**

- All systems can be studied in the *same* framework, no matter what the physical system structures or their models (NN, FS, standard mathematics) are like, or where the system is in the hierarchy
- The data can be delivered not only by a real system but also by a simulator = “hardware-in-a-loop”  
= Integrated modeling and simulation environments possible...



- Signals  $u$  and  $y$  are more or less arbitrary, relationship between them being stochastic; still, some dependence between  $\Theta$  and  $Q$  exists (assume they are mean-centered)
- Use statistical tools to model the dependence
  - MultiLinear Regression (MLR)?
  - Principal Component Regression (PCR)?
- **PLS regression** is defined through  $\frac{1}{k^2} \cdot \Theta^T Q Q^T \Theta \cdot \phi_i = \lambda_i \phi_i$



# Regression

- Applying the latent variables the model becomes

$$F_{\text{PLS}} = \phi \left( \phi^T \Theta^T \Theta \phi \right)^{-1} \phi^T \Theta^T Q$$

and if the quality measure is scalar,

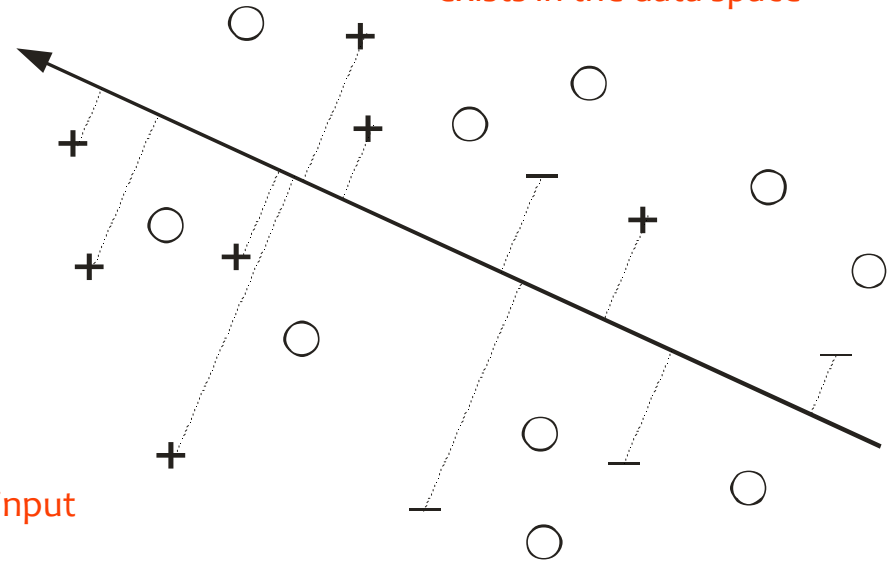
$$f = \frac{\phi \phi^T \Theta^T Q}{\phi^T \Theta^T \Theta \phi}$$

For the estimate one has

$$\hat{q} = f^T \cdot \theta$$

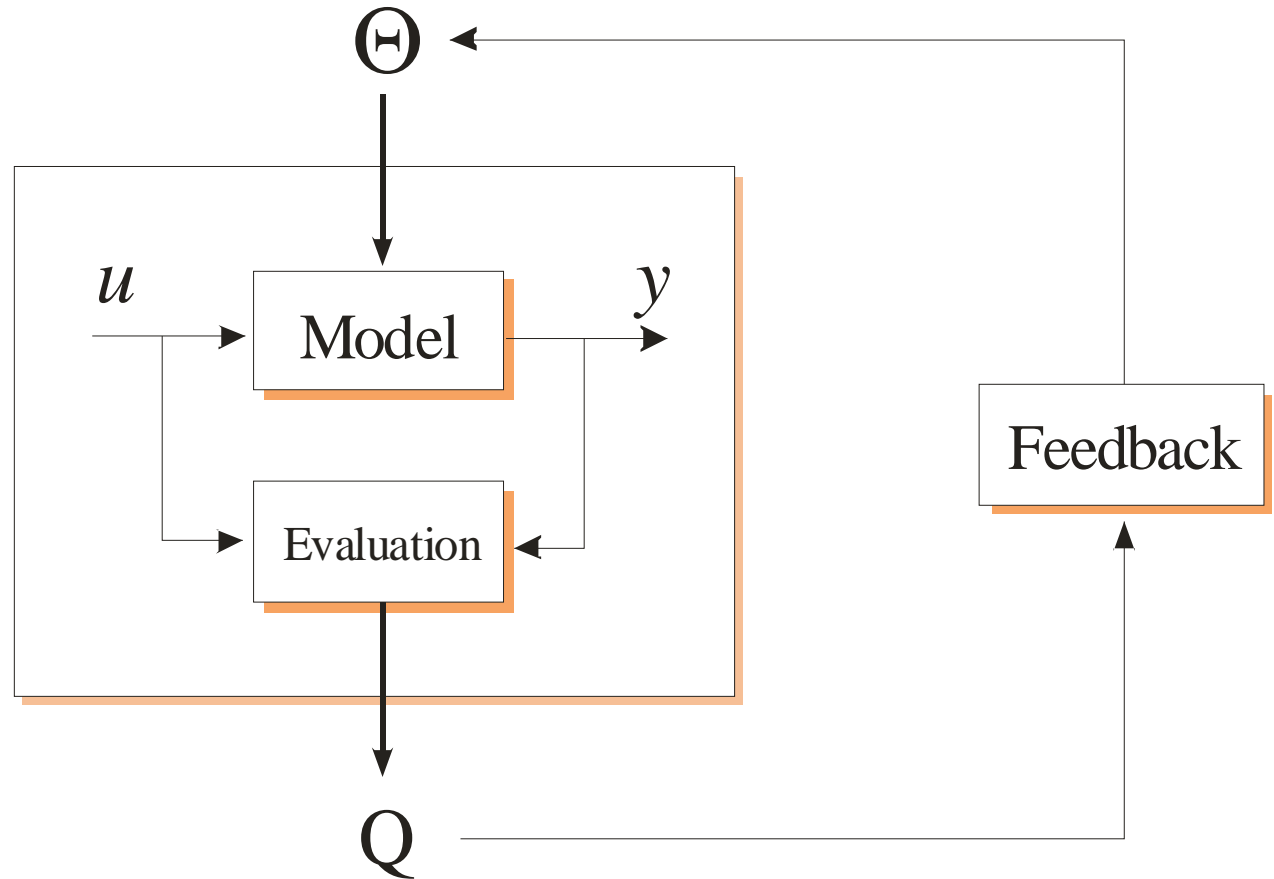
PLS is a linear latent variables based regression method weighting both input and output variables appropriately

If only one quality measure, only one non-trivial direction exists in the data space



# Applications

- Higher-level adaptation scheme (applicable not only for adaptive control):



# Iterative optimization

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- Assume that the cost criterion is defined as

$$\hat{J} = \sum_i w_i \hat{q}_i = w^T \hat{q}$$

Noticing that

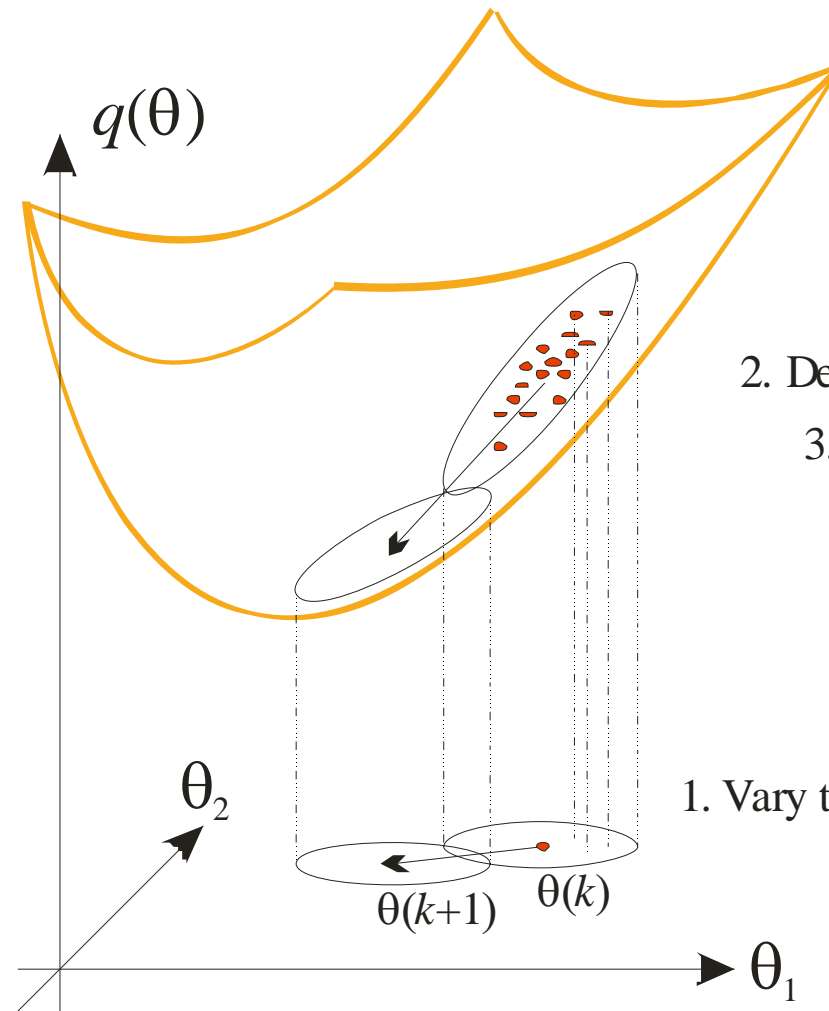
$$\frac{d\hat{J}}{d\theta} = \frac{d}{d\theta} (w^T \hat{q}) = \frac{d}{d\theta} (w^T f^T \theta) = fw$$

one can write the steepest descent algorithm as

$$\theta \leftarrow \theta - \mu \cdot \frac{d\hat{J}}{d\theta} = \theta - \mu \cdot fw.$$



- Visual version



2. Determine the  $\theta - q$  dependency
3. Find the gradient direction

1. Vary the prevailing parameters  $\theta$
4. Update nominal values





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- Adaptive manipulation of models is a notorious problem – why closed-loop identification is no problem now?
    1. First, one is searching for static, not dynamic mapping between variables – there are less variables to search for
    2. It is not actually a closed loop that one is identifying when seen at the higher level – there do not (yet) exist feedbacks between the qualities and qualifiers
    3. After all, one has to think of the case in the perspective of emergent models: It is not individual parameters, etc., that are being detected, but the remaining degrees of freedom in data.



# Theoretical benefits

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- Typically, adaptive control structures are *bilinear*, resulting in theoretical problems:

$$y(k) = \theta^T(k) \cdot x(k)$$

- Now, however, there are two *separate* linear models on different levels:

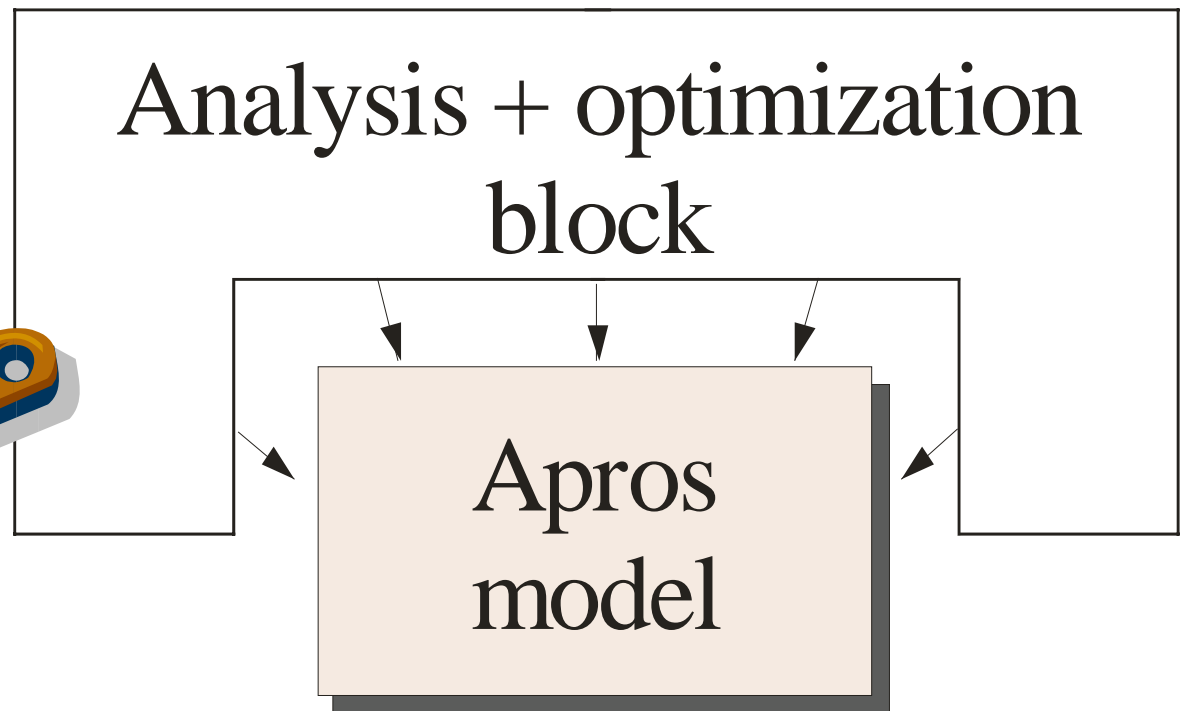
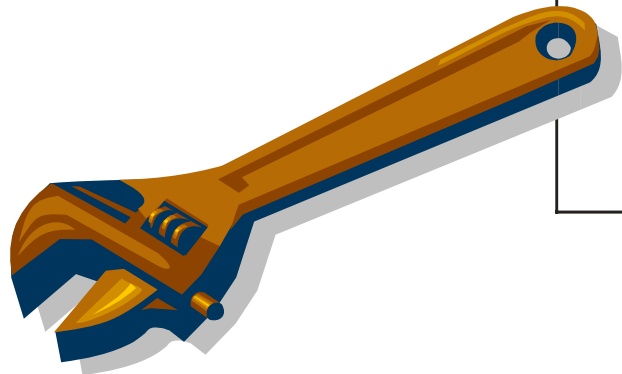
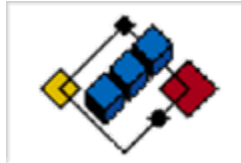
$$y(k) = \theta^T \cdot x(k)$$

$$q(t) = \phi^T \cdot \theta(t)$$

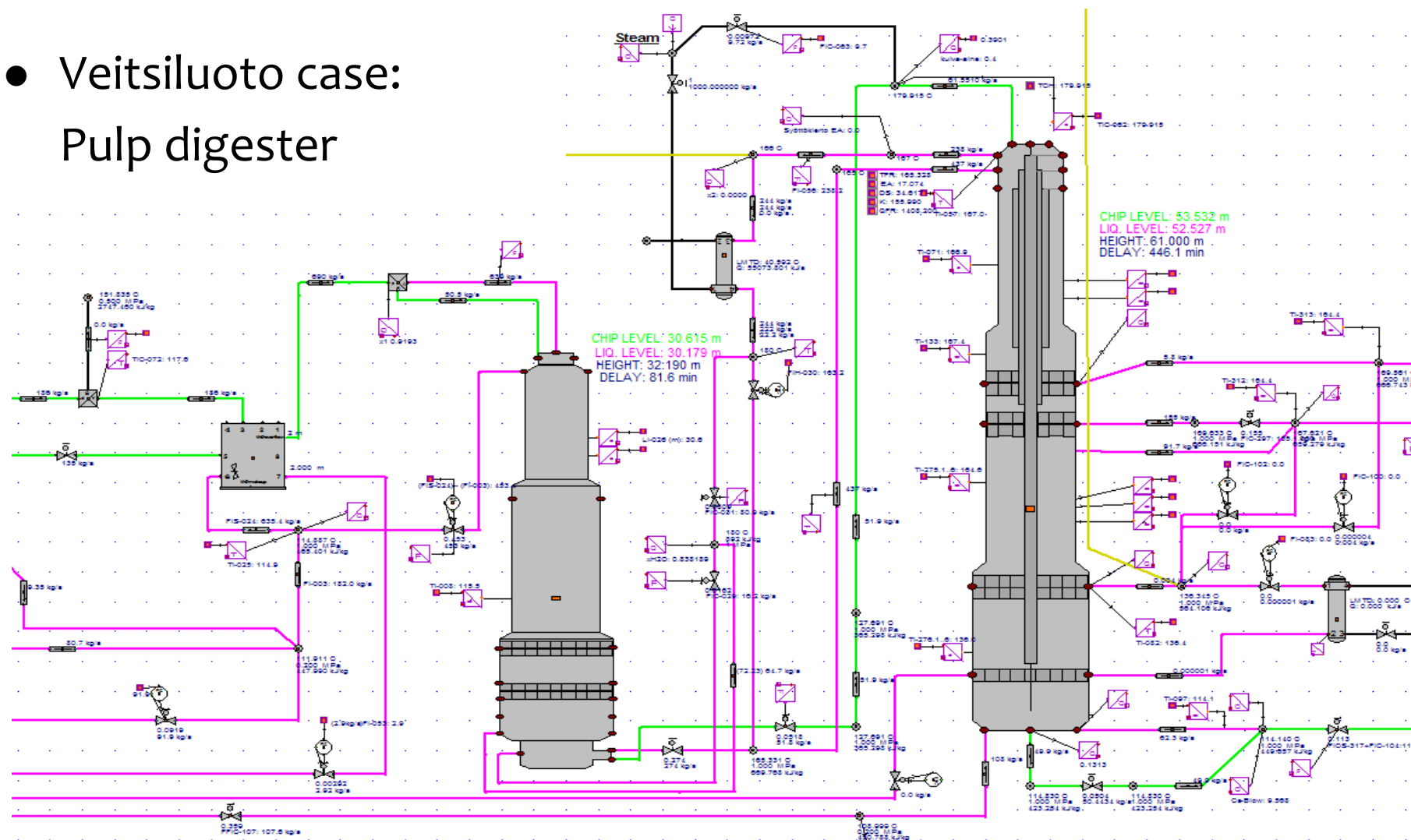
- Explicit distinction between levels makes it possible to reach theoretically simpler analyses.



- Project “Testing Manager”: Evaluate the controller optimization scheme in practice



- Veitsiluoto case:  
Pulp digester



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- 20 parameters (7 PI controllers + 2 model based controllers)
  - 6 quality measures:

- $q_1$ : Kappa number in blow
- $q_2$ : Wash coefficient
- $q_3$ : Digester liquor level
- $q_4$ : Digester chip level
- $q_5$ : Impregnation vessel chip level
- $q_6$ : H factor

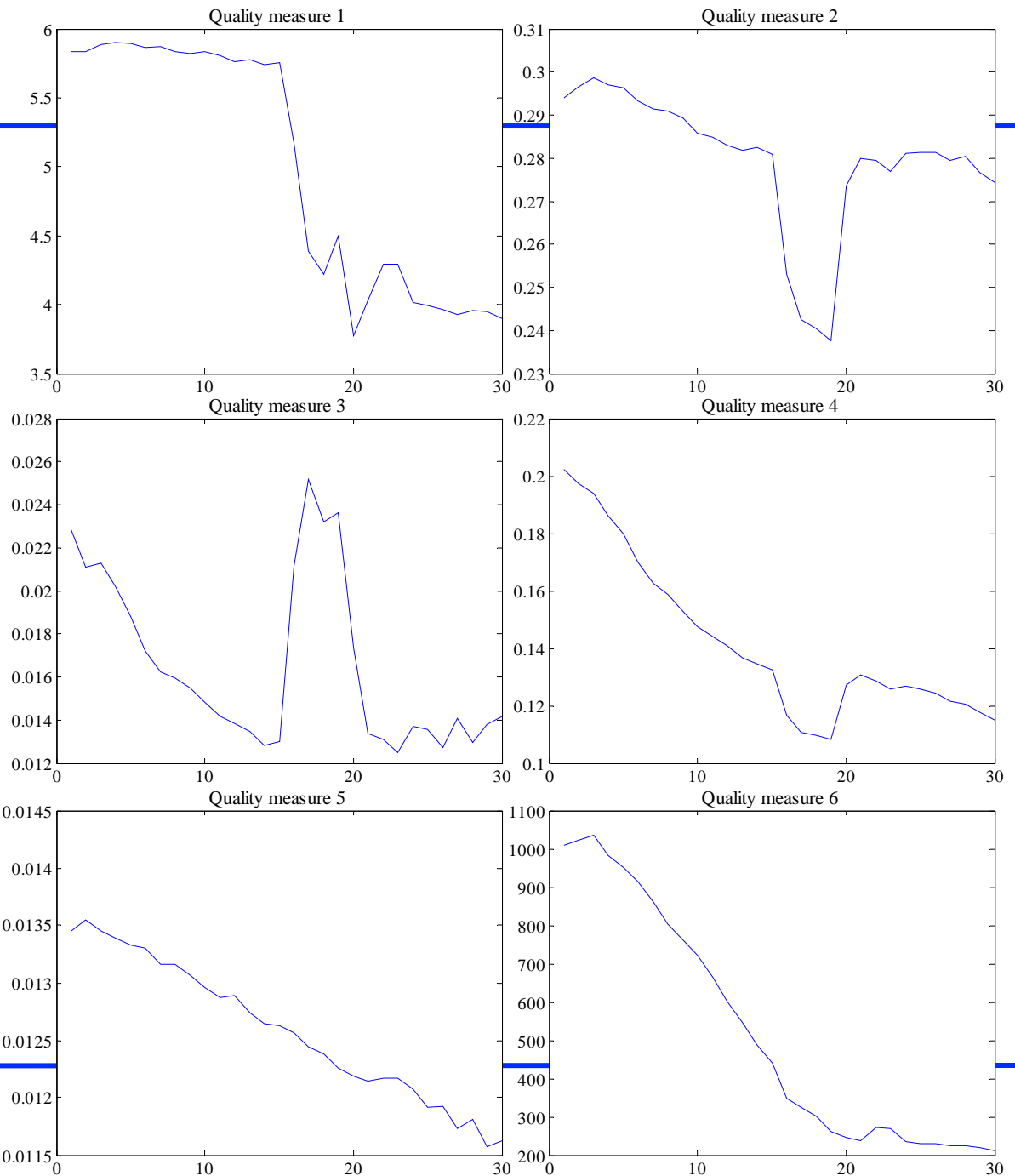
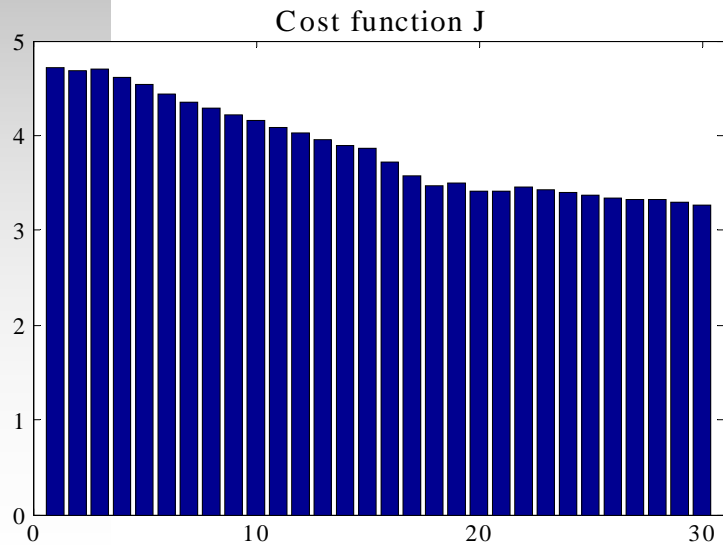
- Cost criteria

$$q_i = \frac{1}{T} \sum_{t=1}^T |x_{sp}(t) - x(t)|, \quad i = 1, \dots, 6$$

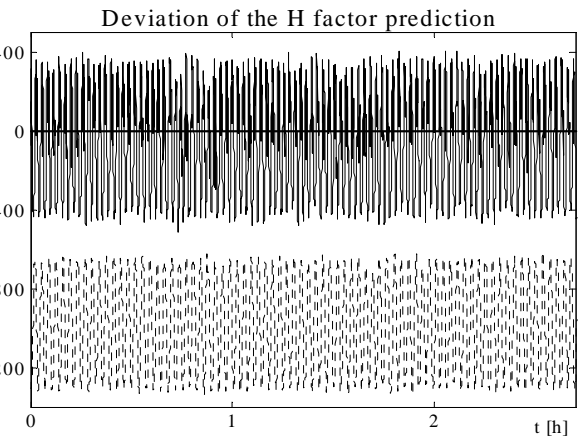
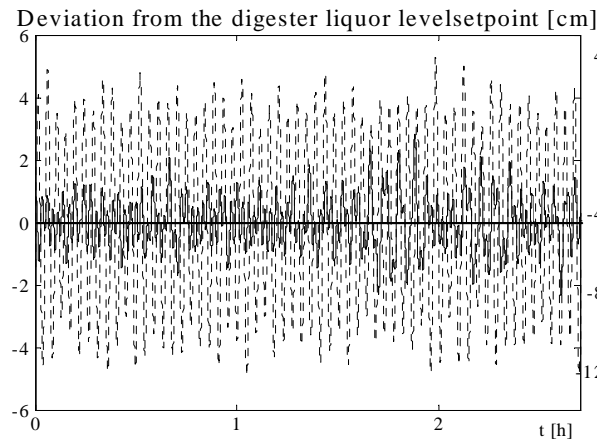
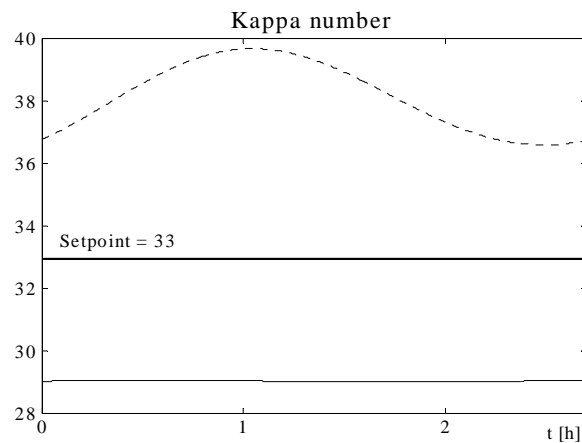
- Optimization based on the PLS model



- Optimization process



- Results promising – various issues where further analysis is needed ...

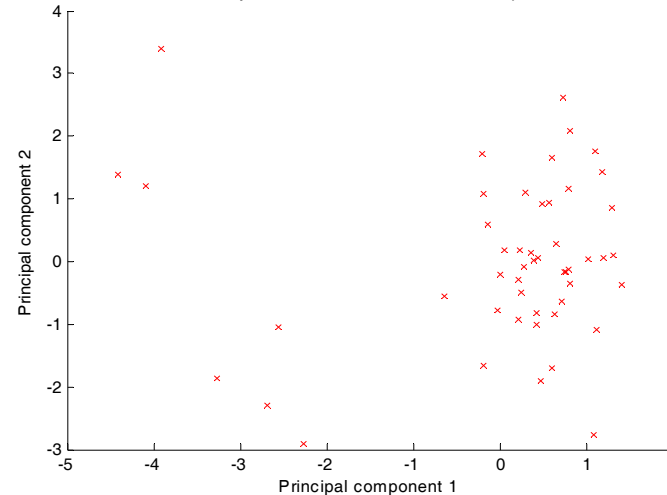


$K$	$q_1$	$q_2$	$q_3$	$q_4$	$q_5$	$q_6$
0	5.0	0.30	0.047	0.27	0.014	982
30	4.0	0.28	0.014	0.12	0.012	219

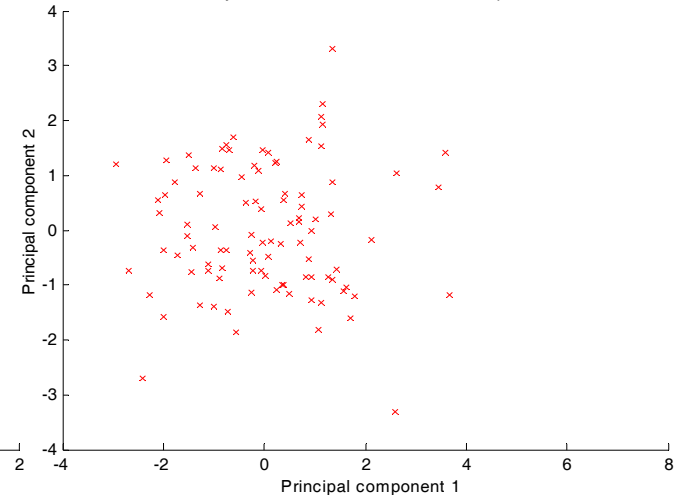


- Test for Gaussianity = check for validity of the linearity assumption

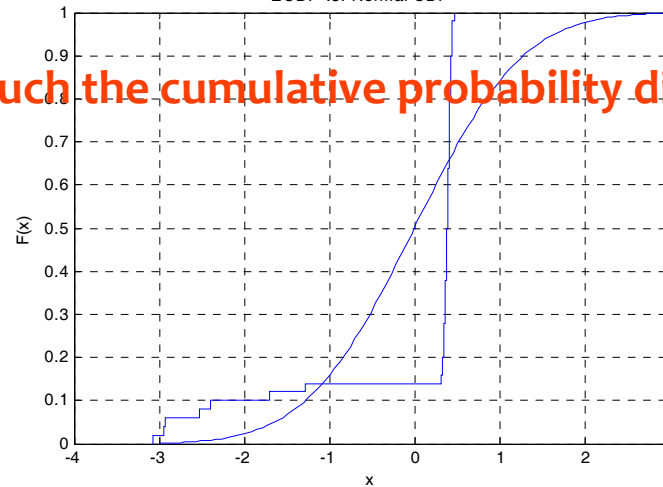
Quality measure distribution: Global step 18



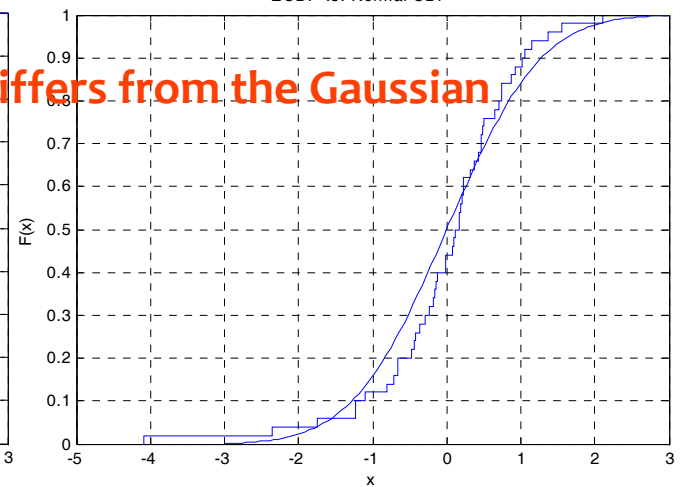
Quality measure distribution: Global step 25



ECDF vs. Normal CDF



ECDF vs. Normal CDF



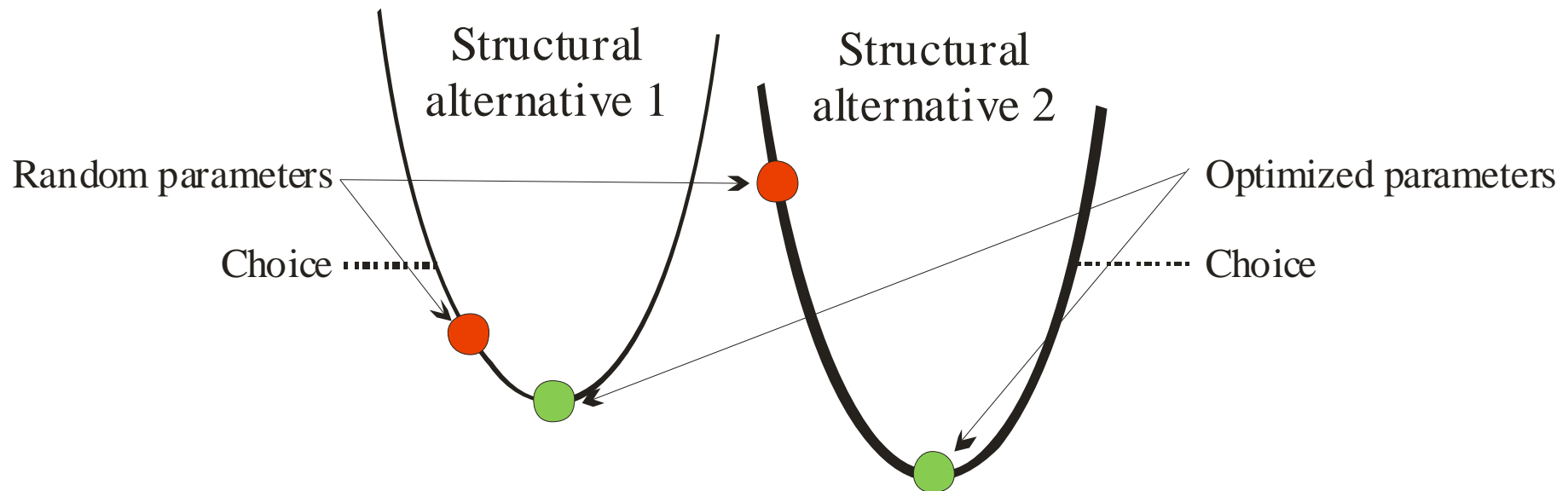
How much the cumulative probability differs from the Gaussian





# Further views

- Gaining intuition on assumptions: What the assumed quality criteria truly *mean* in practice = level of iteration gets higher
- Concrete comparison of structural alternatives:

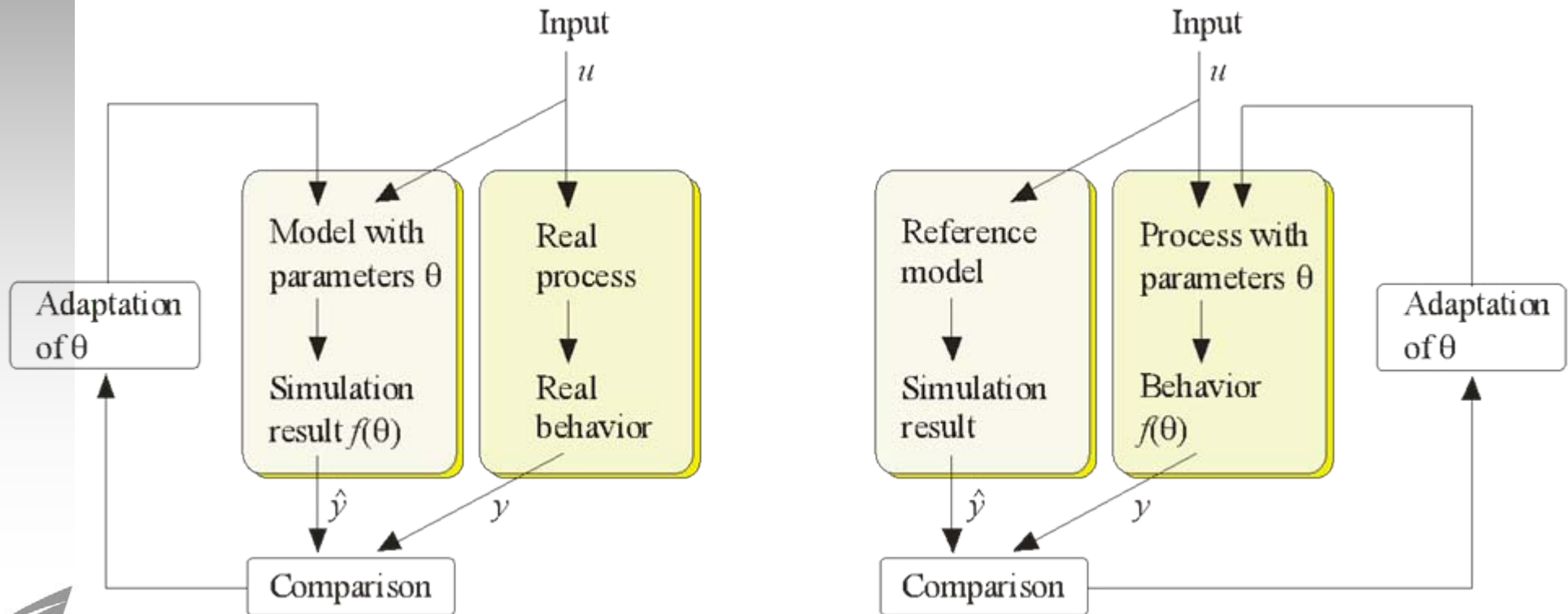


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- Typically, even the expert intuitions of the process performance are vague
  - The experts cannot express what is *good behavior* in the process
  - Selection of quality measures and weighting among them is today heuristic
  - When there is a tool to carry out any quality optimization, **iteration gets from the low level to the high level**
  - It is operators (or practicing process personnel) who now do the iteration, tuning the controllers at the factory floor level
  - Having the new optimization tools this iteration is carried out by the experts, who *tune their process intuitions*



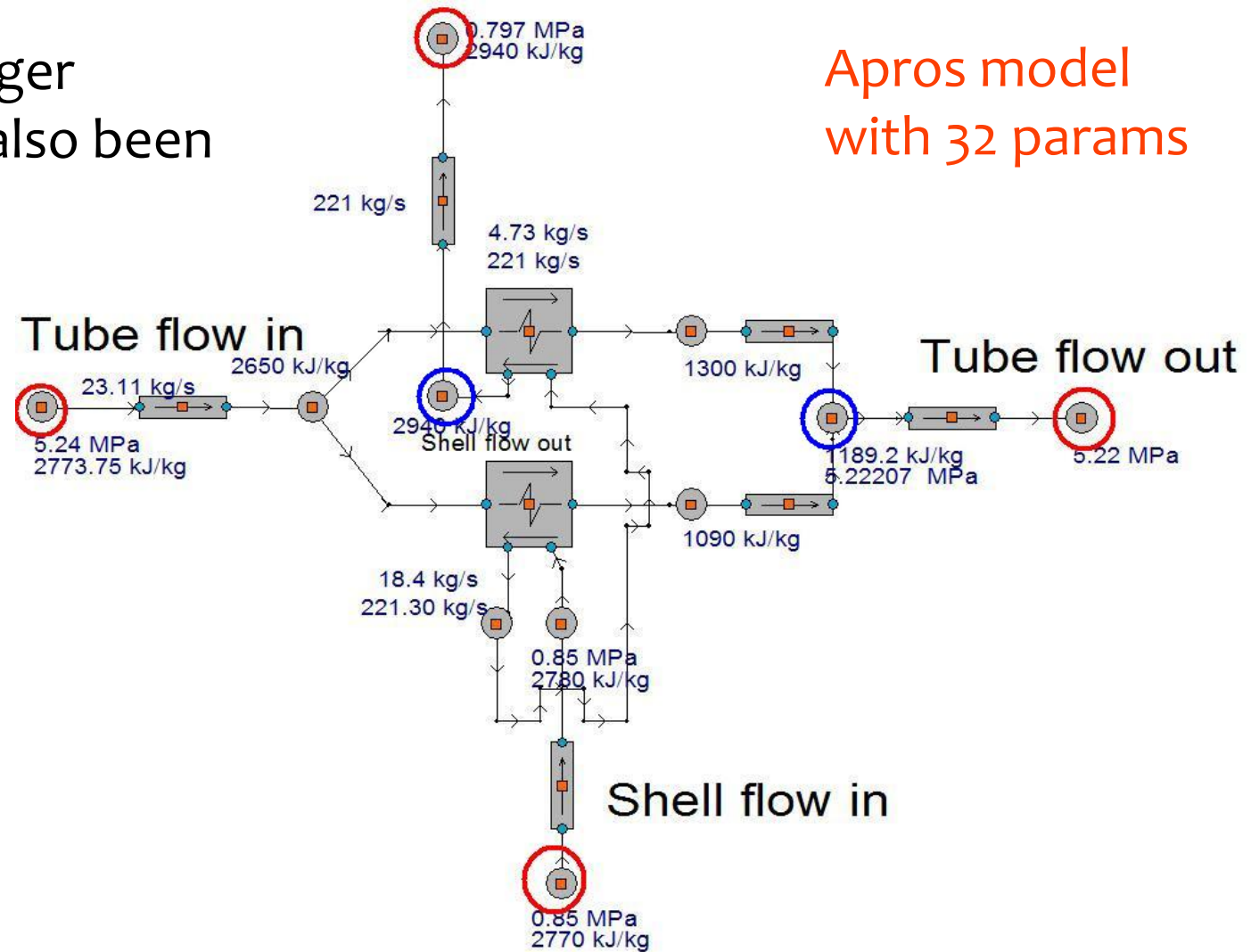
# Opposite view

- The parameters to be optimized can also be in the model – applying the same procedure, model can be tuned



- Heat exchanger parameters also been optimized

Apros model  
with 32 params



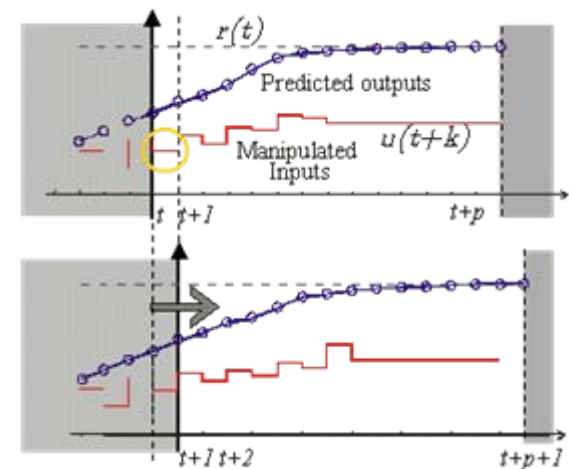
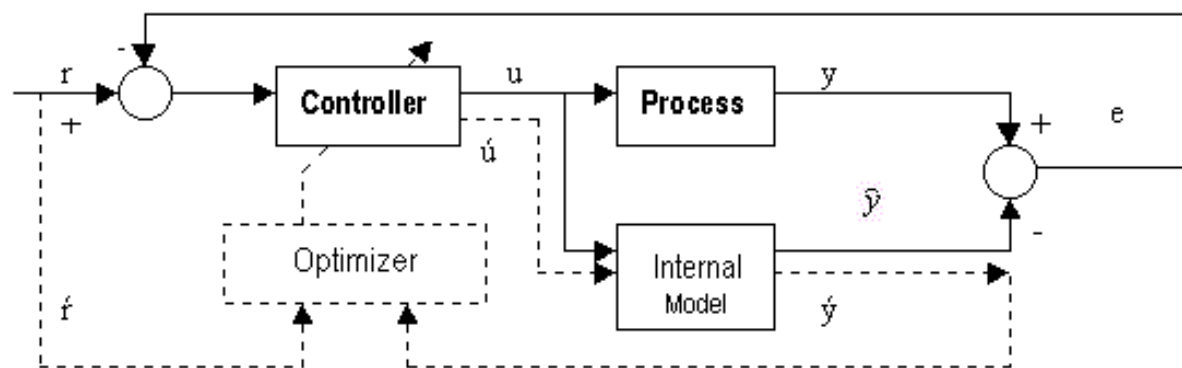
# Simulation-based practices

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- Simulation-assisted engineering practices would boost process design, testing, and training
- However, today's model structures and simulators are too inflexible: Level of abstraction cannot be changed
  - Too accurate models – slow simulations, but also numerical problems, stochastic peaks and transients in simulations
- Perhaps the new scalable model structures make it possible to reach “standardized” plant models
- Key point: The modeling load can be distributed to the device/model suppliers, maybe resulting in the explosion of off-the-shelf up-to-date model components as in Internet
- “Hardware-in-a-loop” can be implemented



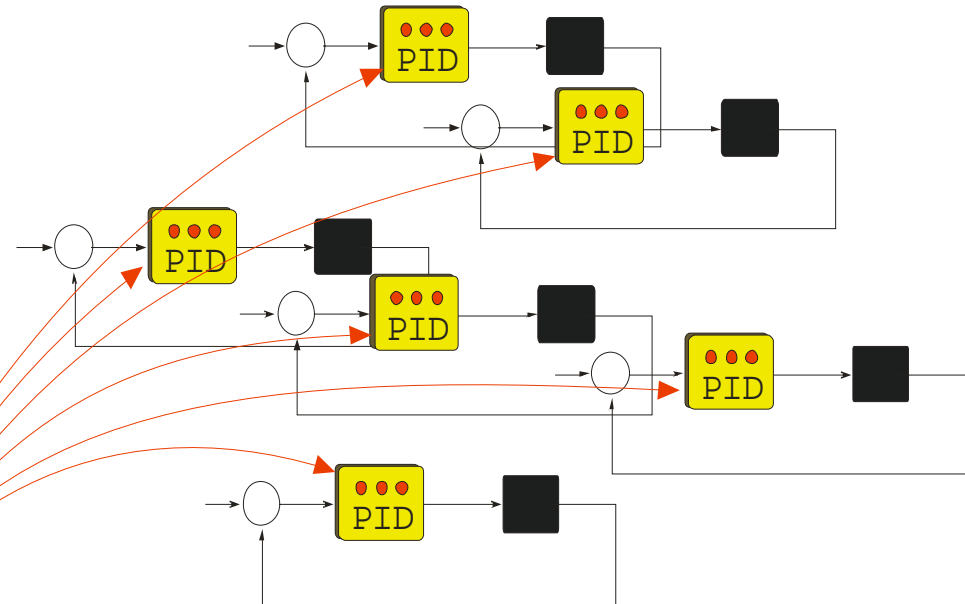
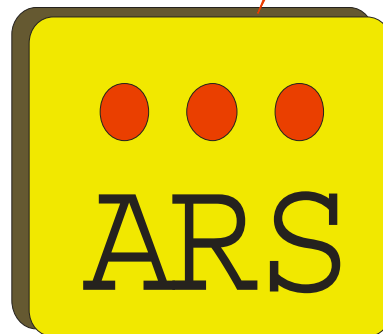
- Again, there is a close connection to traditional practices: Model Predictive Control (MPC) is among those modern methods that have become widely adopted in practice – model is needed to predict process behavior
- Good, efficient models are needed to implement these control schemes



# Extending the operator view

- Explicit optimization is often not possible
- The *slopes* of criteria can still be found
- The tuning knobs can be made to reflect *relevance*

Lower-level controllers tuned in a coordinated manner according to a model where control parameters affect qualities



# “Higher-level PID’s”

- Power of PID: *Intuitiveness*

- Proportional action
- Integrative action
- Derivative action

- Correspondingly:

- “Accuracy action”
- “Robustness action”
- “Speed action”

To be accepted not too  
*much* can be changed

Now, good match with the  
operator’s mental view?





# Evolution in technical systems – *in general*

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- Basic observation: The more there is information and understanding, the more there is exploitation
- The observed correlations between signals are exploited by implementing interactions and feedback controls
- External disturbances and environmental changes are taken care of better and better, system becoming better in balance
- Finally, the system becomes more or less fully connected, “pancausal”

Evolutionary systems typically evolve towards being more and more cybernetic



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- The cases studied before still do not address the real complexity of systems with *structural adaptation*
  - One would like to understand the underlying structure and dynamics of *evolutionary cybernetic systems*
  - The same pressures govern behaviors in very different phenospheres:
    - Social, economical, and technical systems that are optimized by humans
    - Biological systems that are optimized by Darwinian evolution, etc.
  - It turns out that still higher levels of abstraction need to be employed: Earlier, the abstract flows of information rather than the physical flows in the cybernetic system were studied – now study the level of “knowhowflow” ... What?!



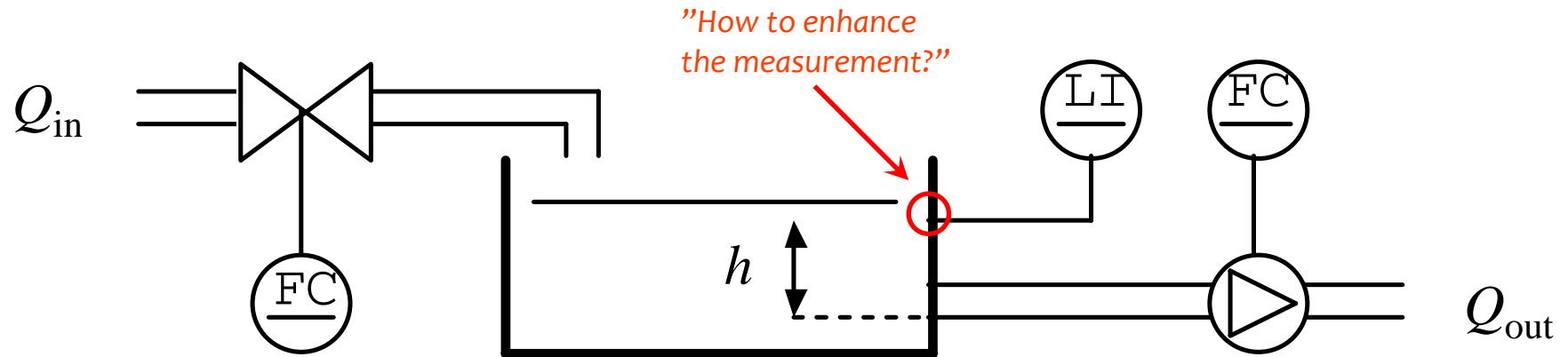
# From quantitative to *qualitative* enhancements

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- Assumption: Automation systems become more and more cybernetic, even though continuity cannot be assumed
- Very little can be said about evolutionary processes, or “cybernetization”, in general terms – it is about *innovations*
- Innovations are unique and cannot be captured in the statistical neocybernetic framework
- Some visions are presented below, and a case study from a real plant, visualizing the *fractality of developments*
- Basic rules – where to head towards: **Increase stiffness** – where there is variation, more resources should be invested; **relieve tensions**, if desires and reality are in imbalance



# Example: Process levels



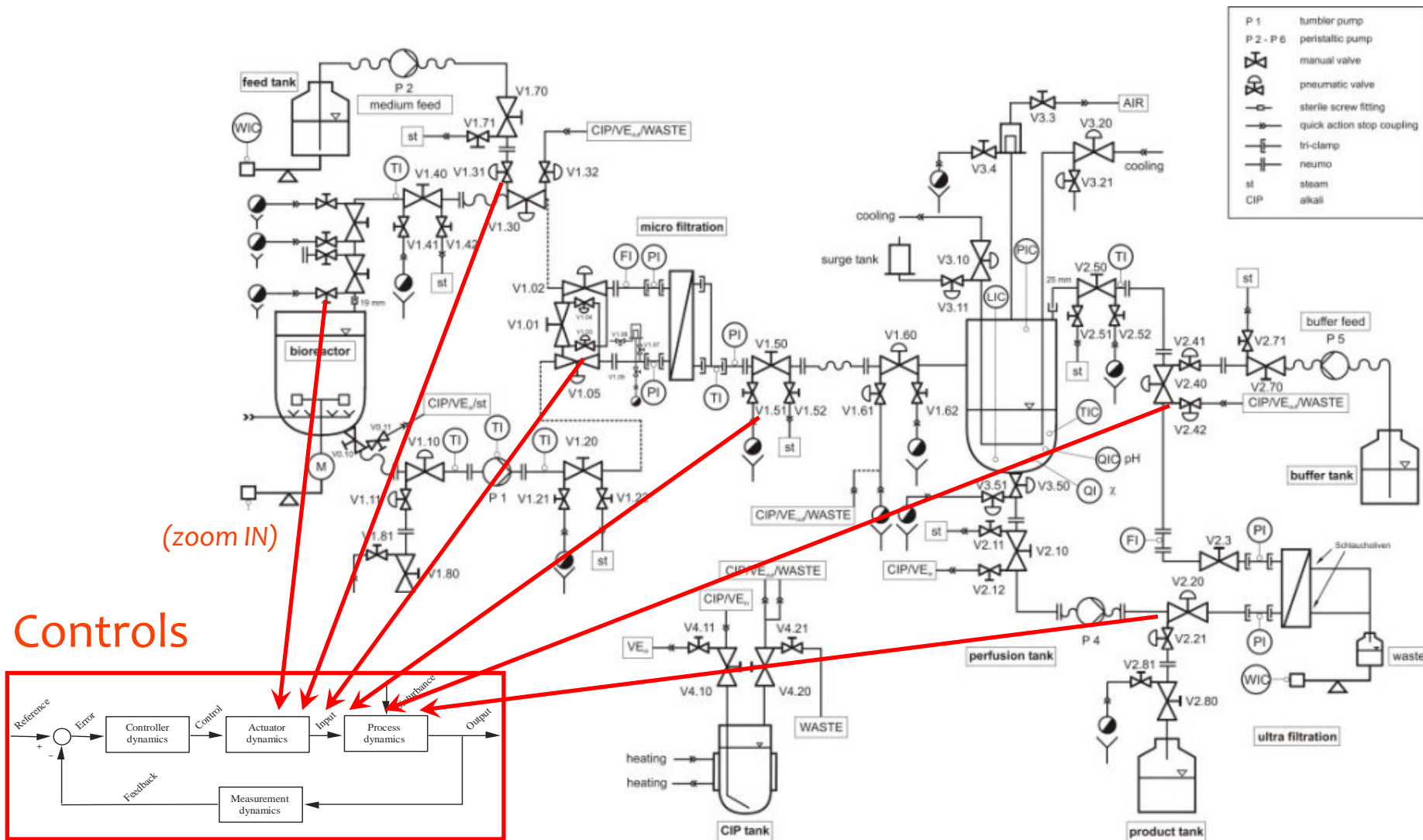
- *Physical level (formation):* Input  $Q_{in}$ , output  $Q_{out}$ ; based on the actual process structure and its energy/matter flows
- *Information level (metaformation):* Inputs  $Q_{in}$  and  $Q_{out}$ , output  $h$ ; based on what can be measured and what can be affected
- *Knowledge level (metainformation):* Inputs are now the tensions of the system, outputs are its resulting properties



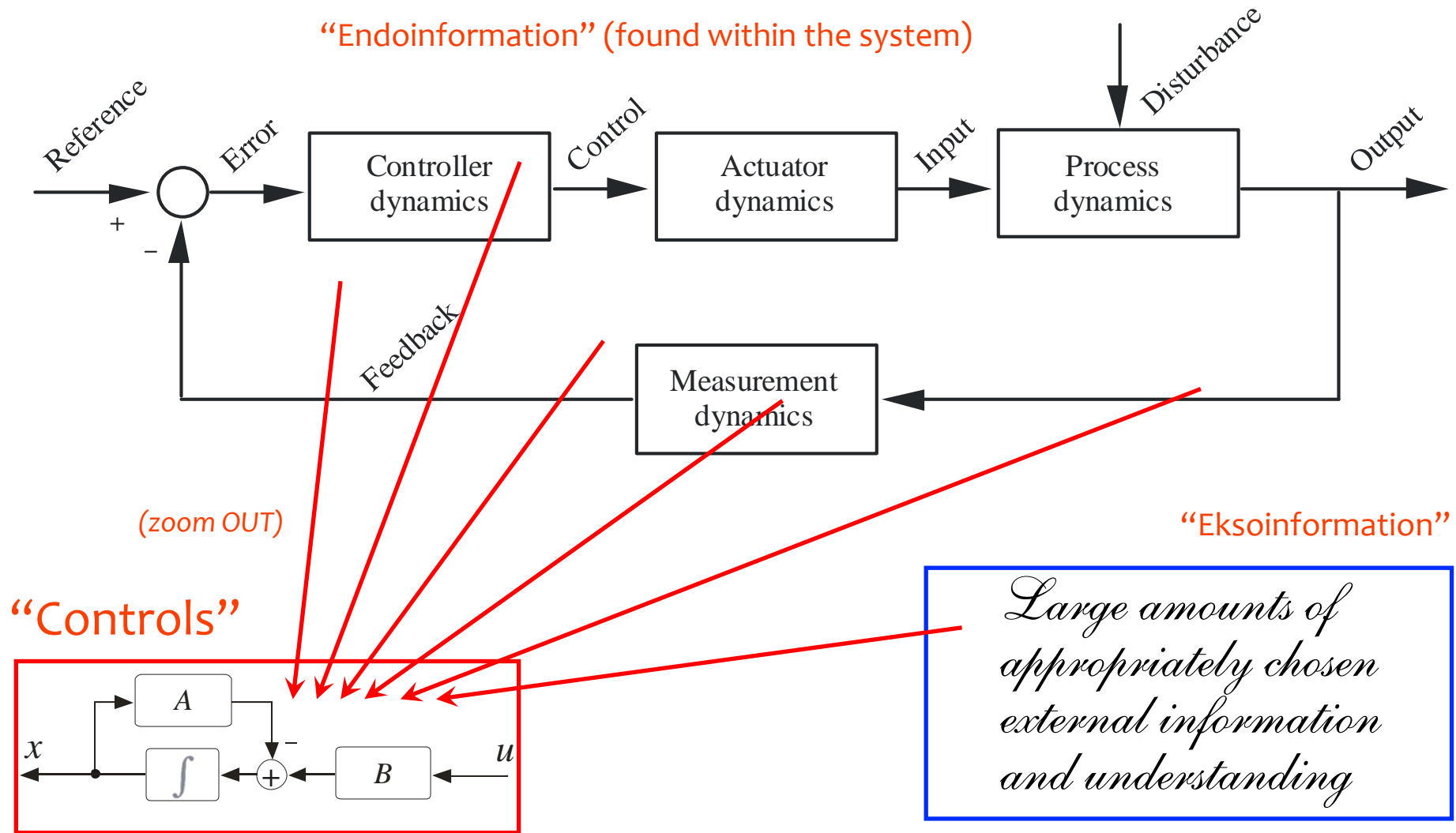
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- There are some structural similarities typically found in different levels of system flows
  - On the *information processing level*, it is the **feedback control loop** that is typically found (in some form or another)
  - On the *knowledge processing level*, the behaviors can be captured in the **cybernetic model**
  - Any part of the system can be in “informational imbalance”, constituting a tension for further “dynamics” in the system
  - The knowledge level cannot be mechanized: Exogenous information is needed that is not available in the process
  - Expertise and “common sense” is needed to select the information and to exploit it appropriately



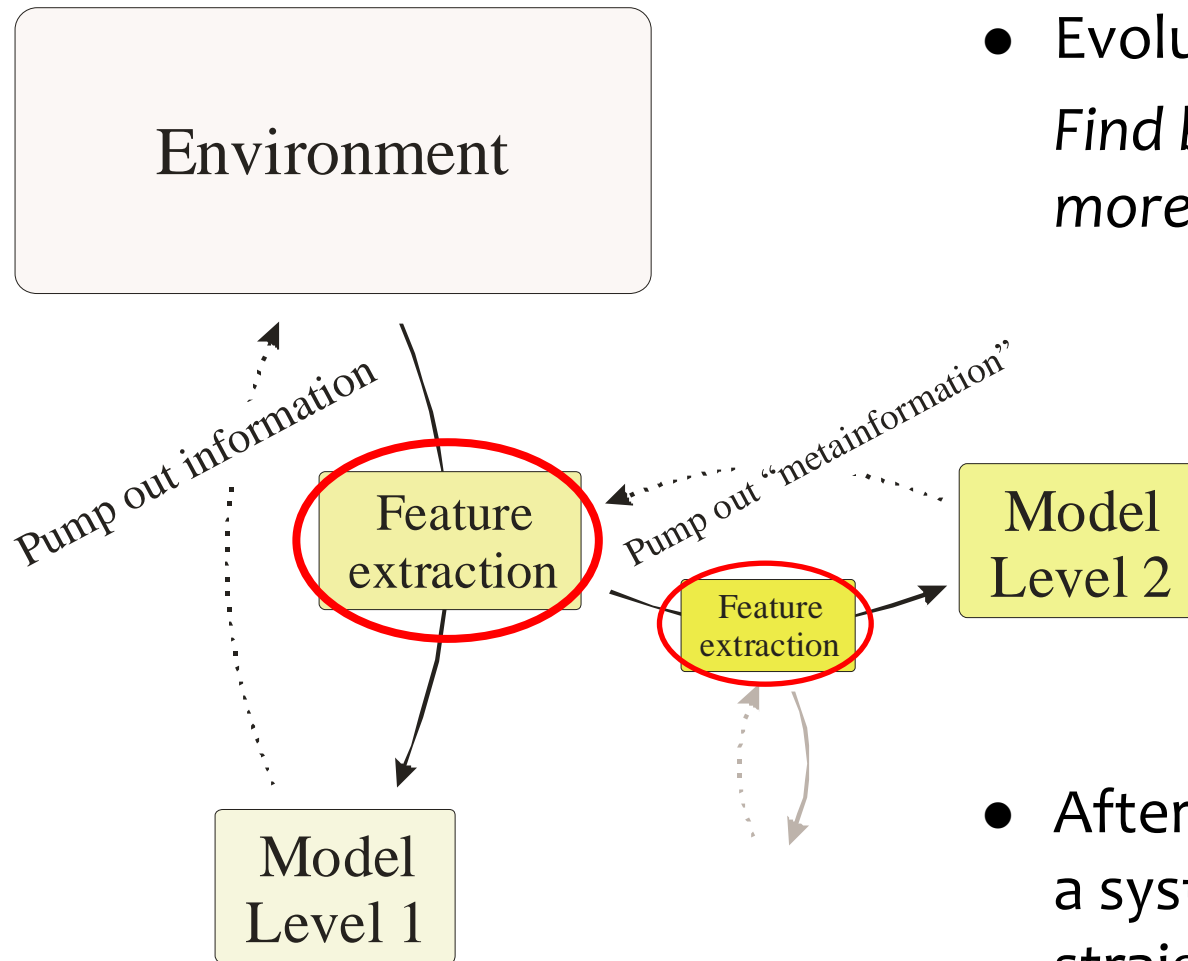
# From process flows to information flows ...



# ... From information flows to “knowhowflows”



# Yet another view: Role of semiosis



- Evolution goal focused:  
*Find better – streamlined – more effective features*

- After that, adaptation in a system is more or less straightforward





# Case study: “Cybernetization” of a plant

- Pyhäsalmi Mine in central part of Finland
- Copper, zinc and sulphur concentrated by *flotation*

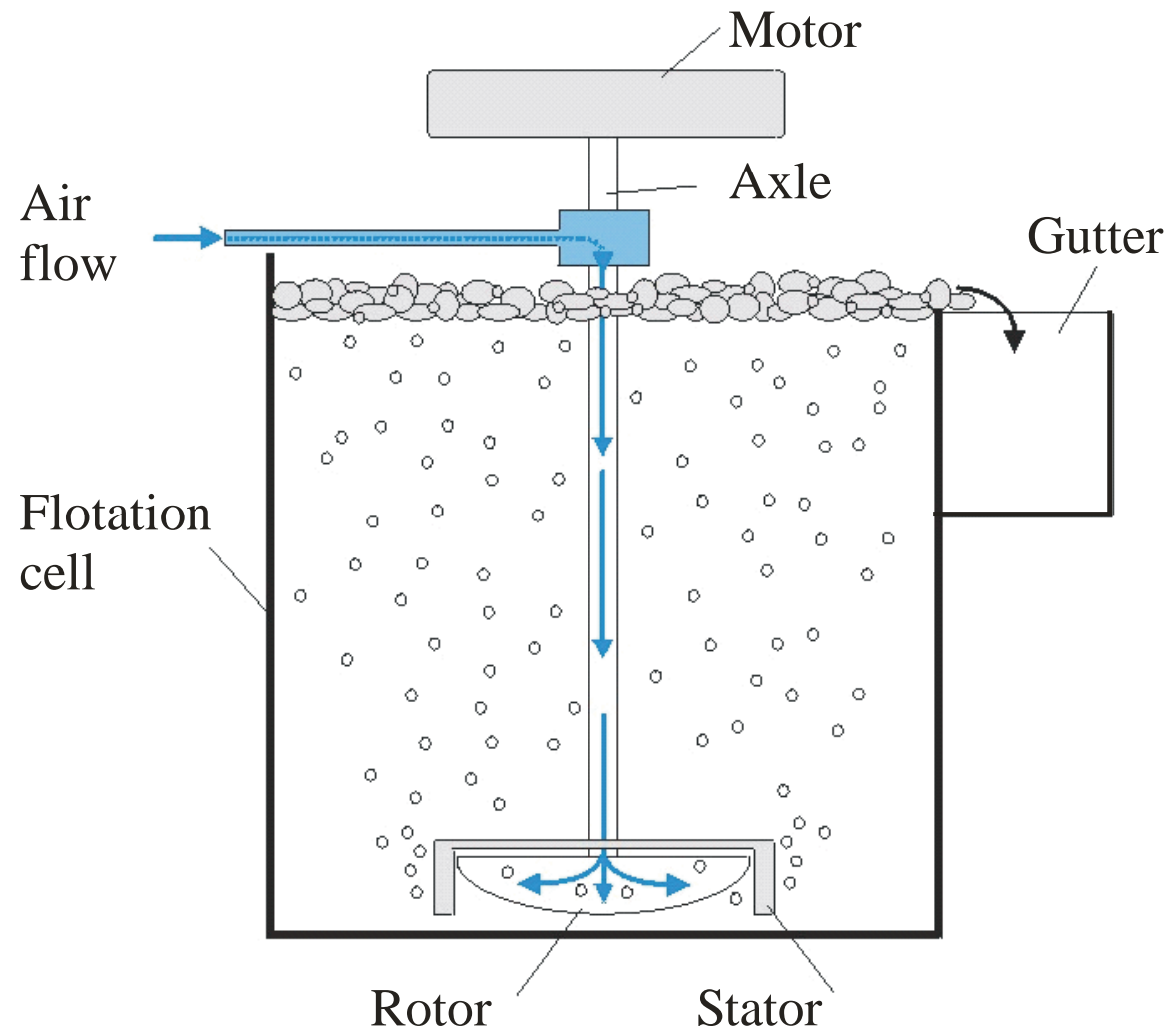
**Simple?**



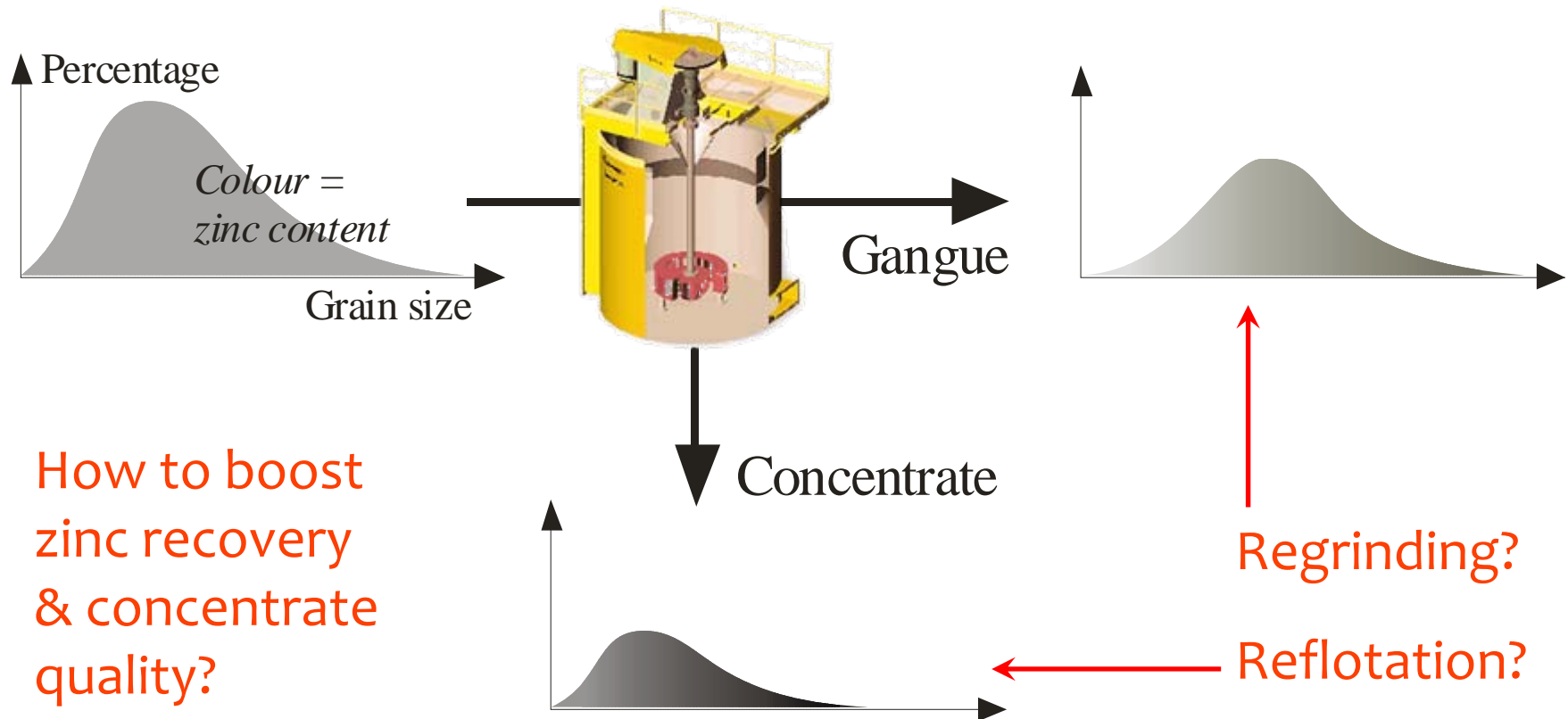
Find the balance of costs and gains, possibilities and needs!



- Flotation cell:  
Air bubbles bring the hydrophobic mineral grains onto the froth surface
- Simple?
- Increasing understanding makes things more and more complicated...



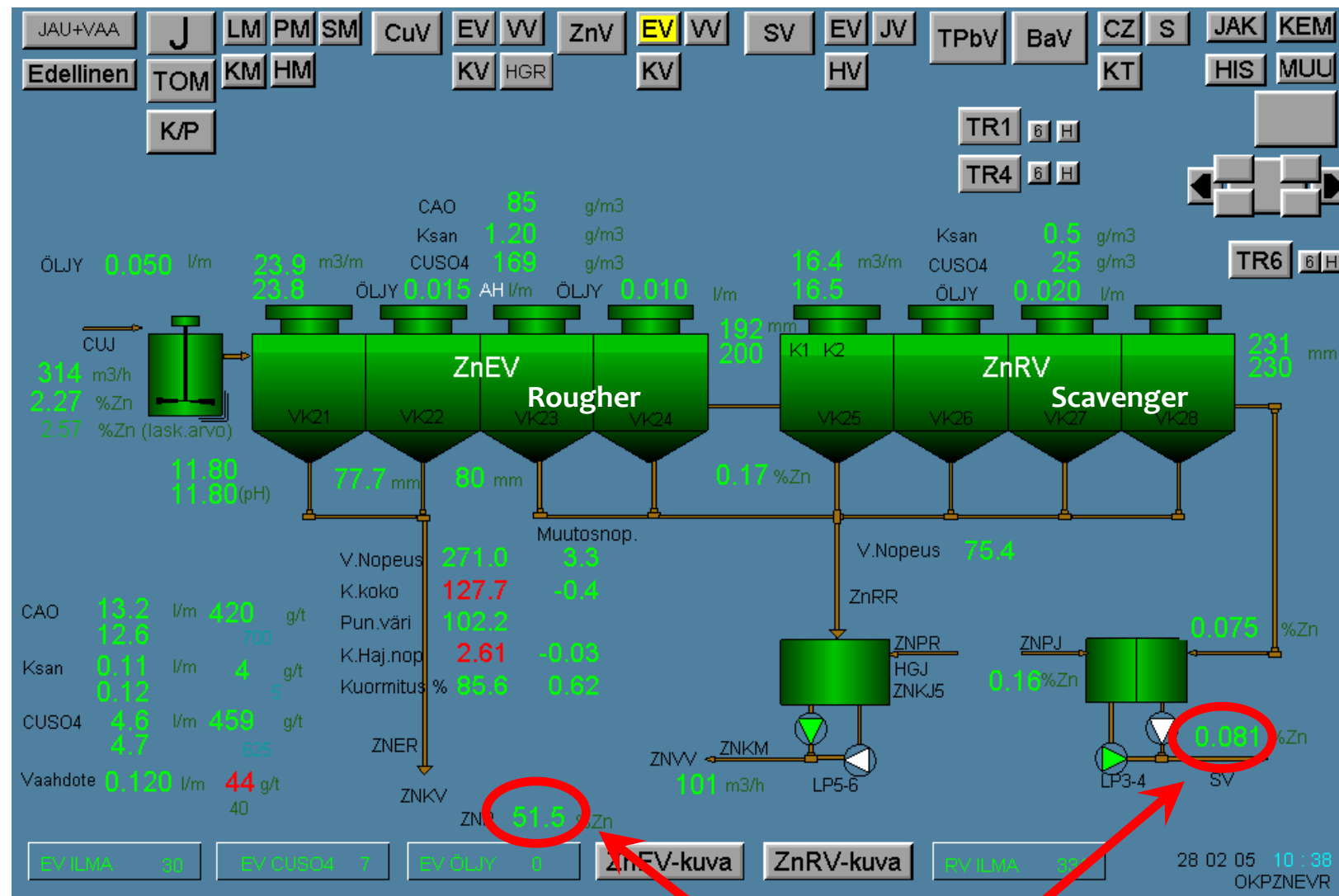
- Closer analysis: How the need for more sophistication in the flotation process emerges



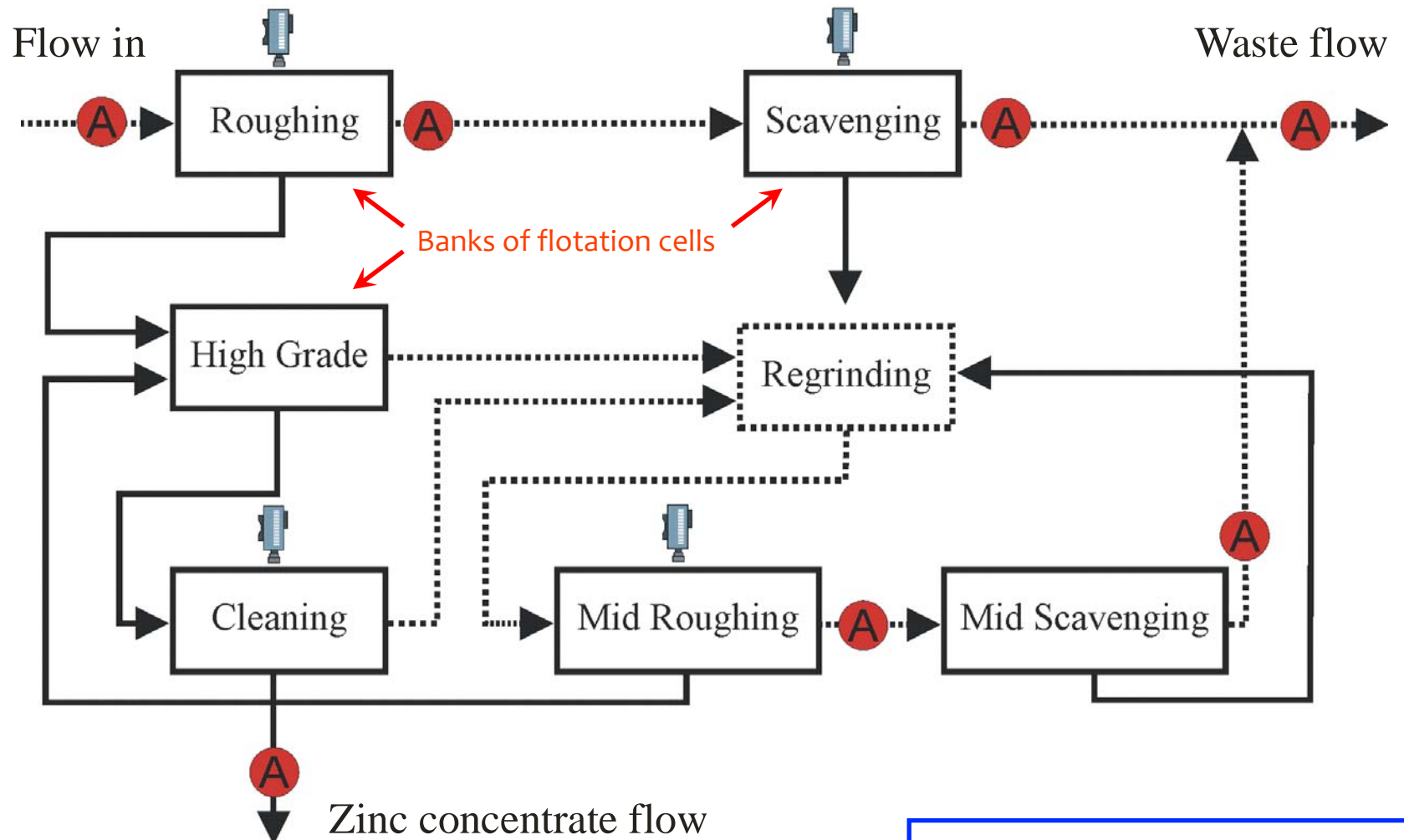
How to boost  
zinc recovery  
& concentrate  
quality?



# Optimization between grade and recovery



# Zinc circuit



Final structure is  
“self-organized”!

- 
- Flotation circuit designs vary in structure depending on the type of mineral, degree of liberation of valuable minerals, intended grade (purity) of the product, and its value
    - The first rougher stages produce a good grade concentrate, but recovery is only medium, the second rougher stage is designed to maximize recovery
    - The scavenger cells increase the recovery when particularly valuable minerals are being treated, reprocessing the rougher waste
    - Cleaner cells maximize the grade of the final concentrate, reprocessing the concentrate; the volumes are lower than in rougher stage
    - Regrinding is needed to liberate zinc from larger grains where there is waste minerals mixed with valuable minerals
  - The designs are plant-specific, and typically evolve during the life-span of the plant





# Information processing level

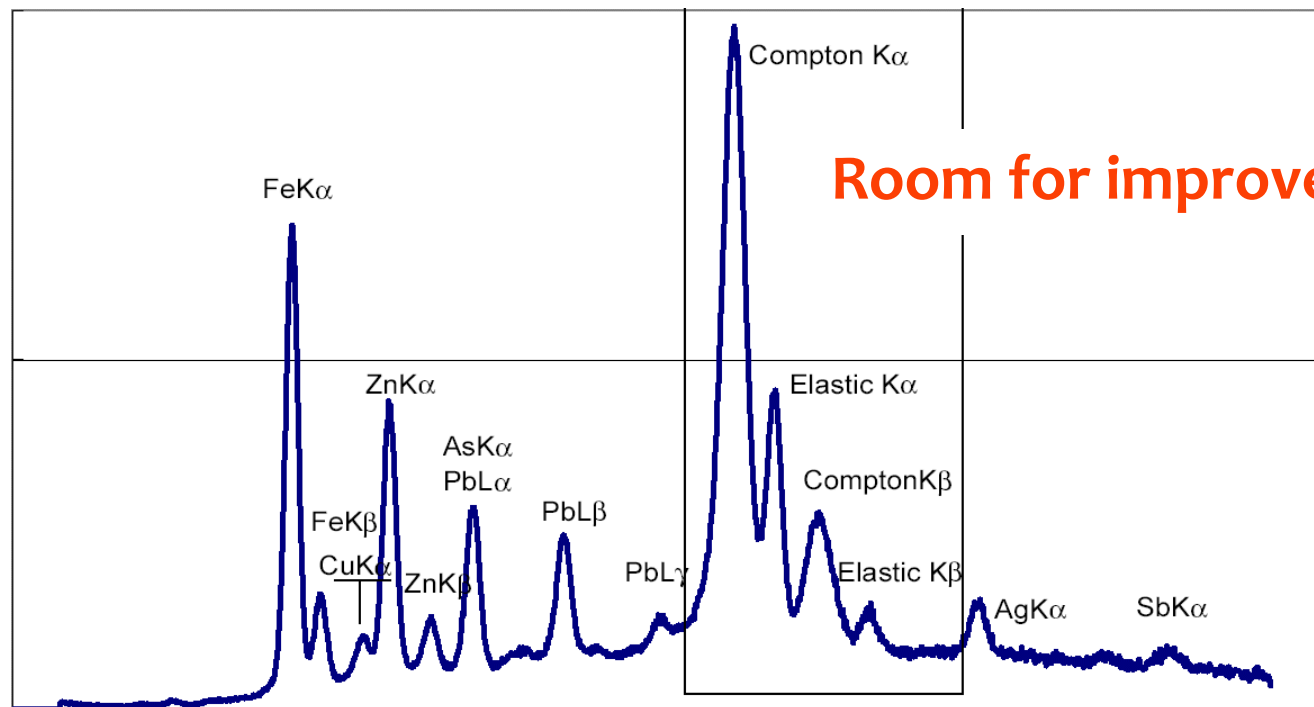
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- Understanding the functional structure of the process also makes the physical structure become more sophisticated
- Above the physical level, information processing structures determine another level of complex networks
- It is not only understanding the structure in general – one also needs to know the volatile current state
- Goals: Understanding the signals and measuring them; later finding their relationships + utilizing these in controls
- First step: Efficient, accurate data capture, transfer, and storage – then exploitation of the information, or control
- For example, concentration measurements are carried out using an *X-ray analyzer*



# X-ray fluorescence analysis of slurry

- In principle, spectra are uniquely determined by atoms
- In practice, problems because of uneven slurry densities, imperfect sensing technology, external noise, ...





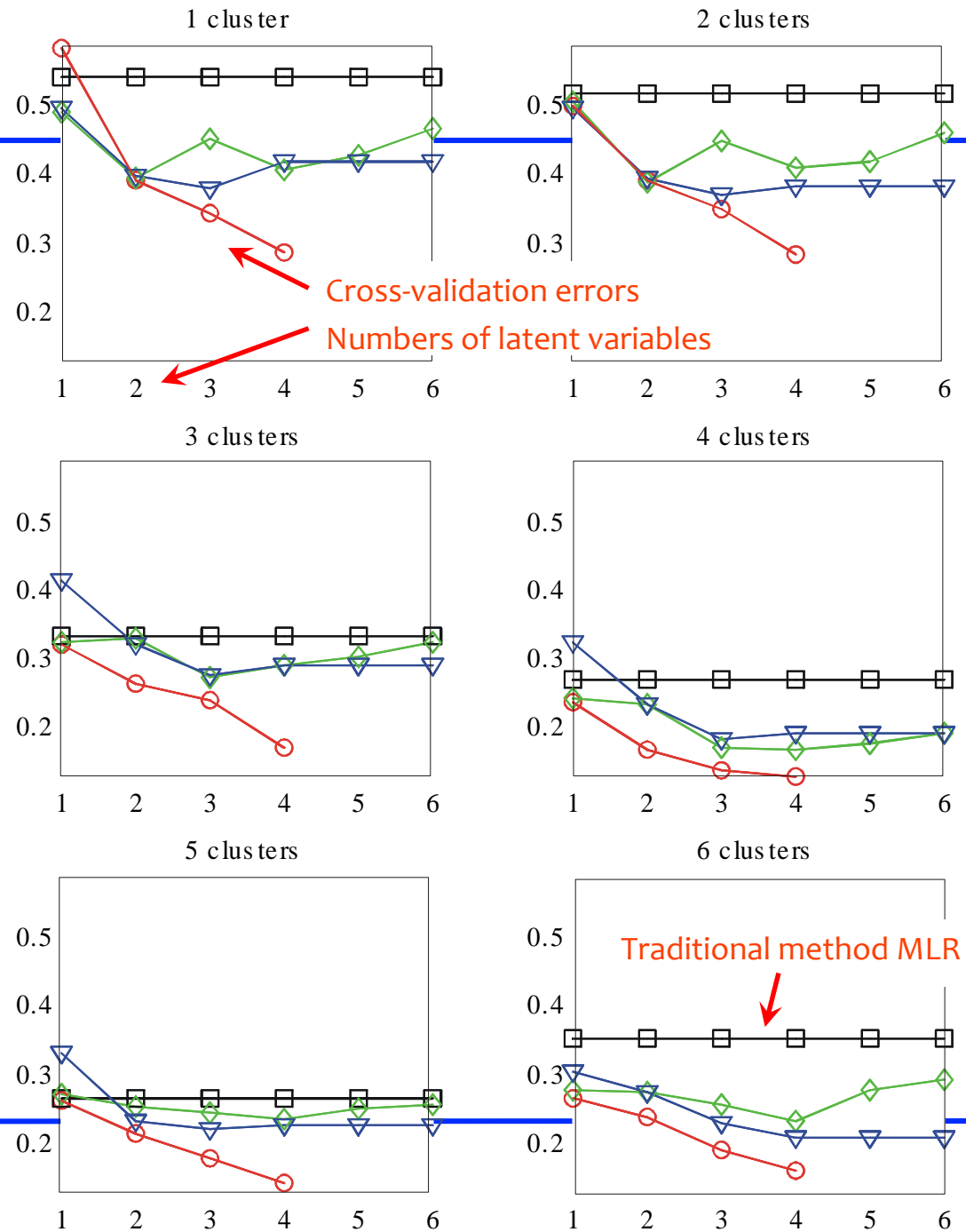
- Calibration model needed from measurements to atom concentrations
- New approaches being developed...
- Statistical multivariate models:

- MLR

- PCR

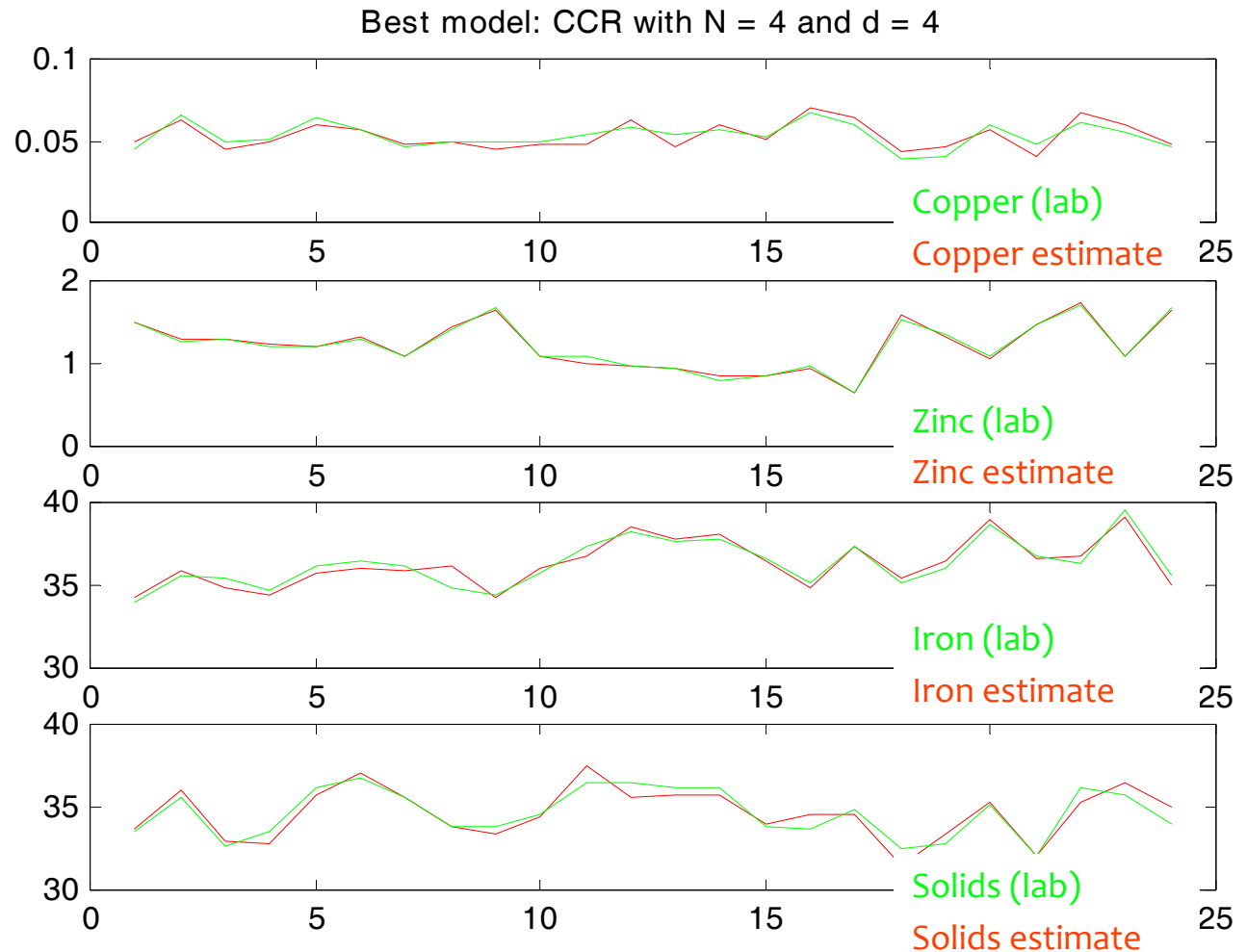
- PLS

- CCR



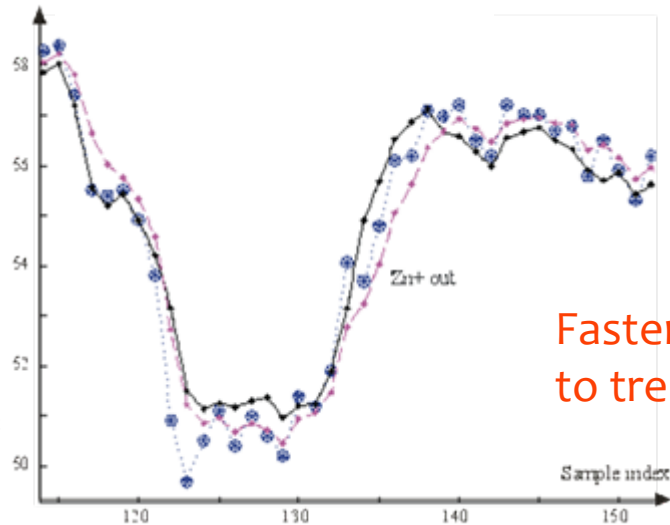
# More accurate measurements reached

- Estimates OK, but...
- Measuring using X-ray analysis is slow – there is a 20 min interval
- Additionally, the data has to be filtered

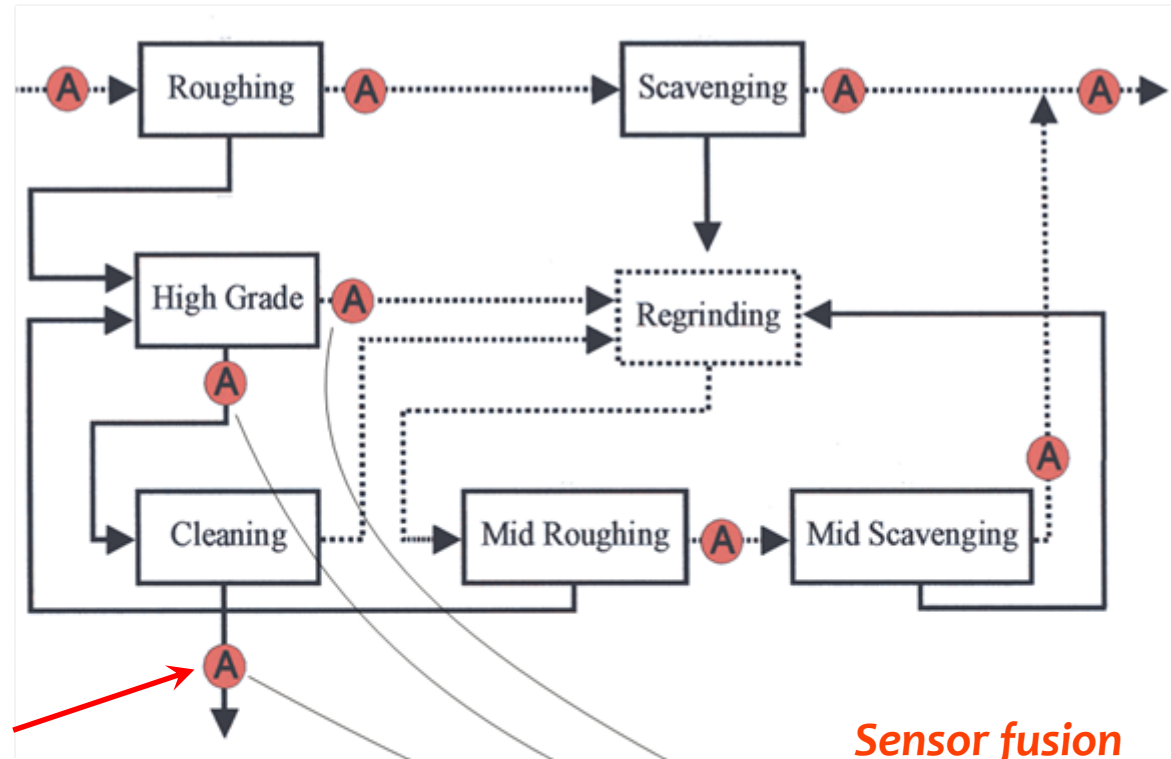


# Towards “smart devices”

- Correlations between signals can be exploited to reach better estimates



Faster reactions  
to trends

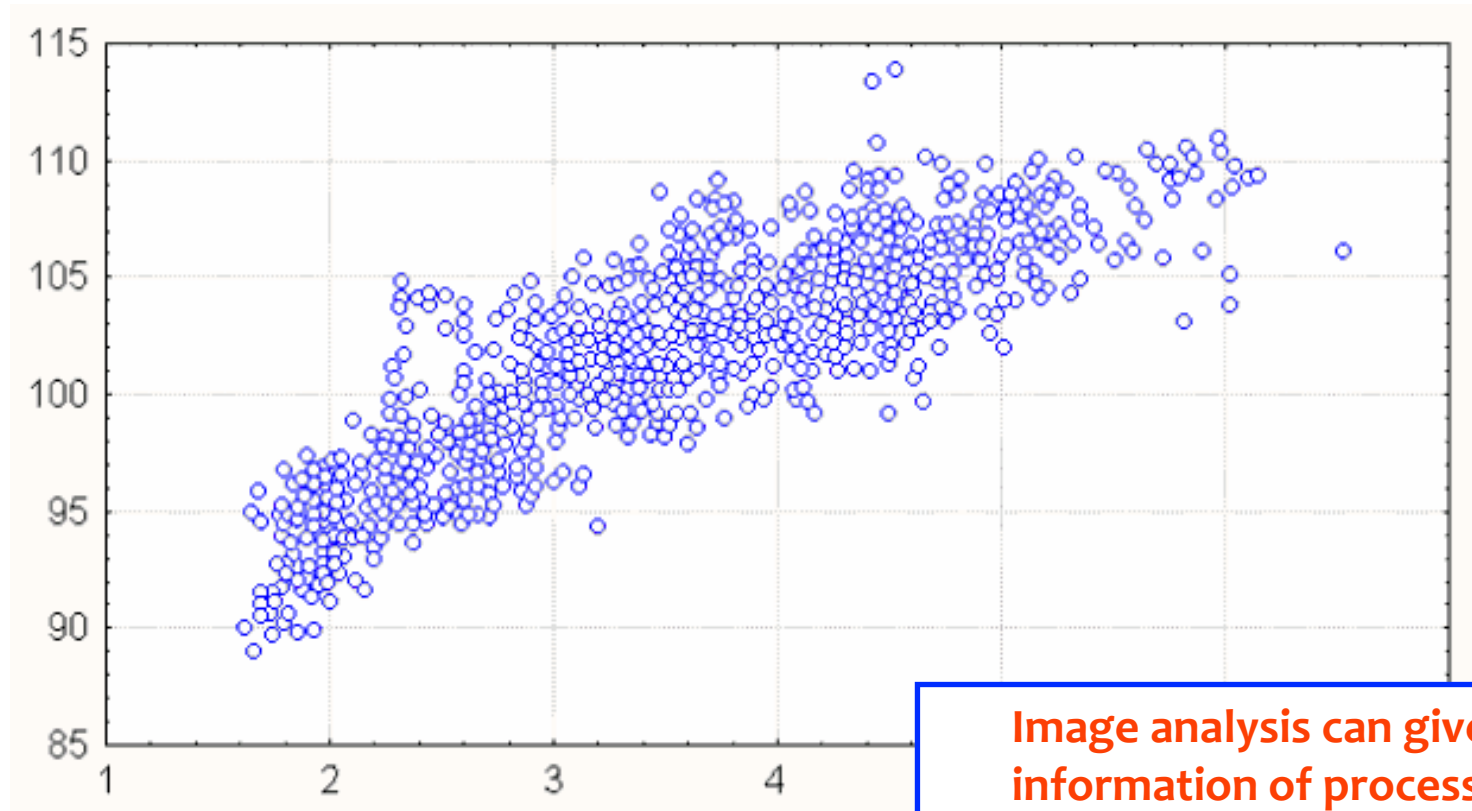


Sensor fusion



# “Data mining” for mining data

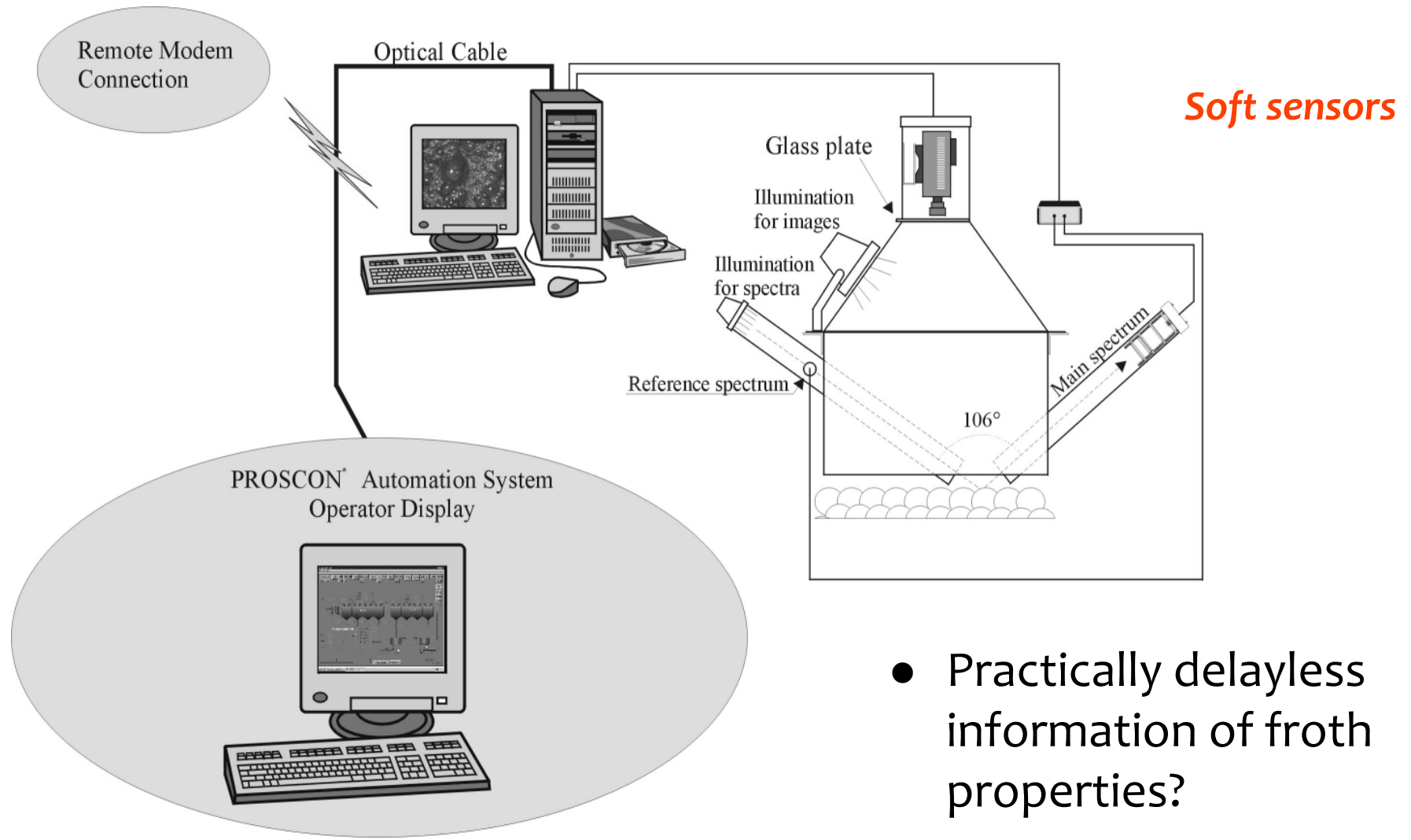
- New understanding: Correlation between incoming (scaled) zinc concentration and froth “redness” in the rougher



**Image analysis can give  
information of process state  
also between X-ray analyses –  
utilize this!?**



# Projects “ChaCo”, “Väsy”, “Äksy”, “Rike” ...

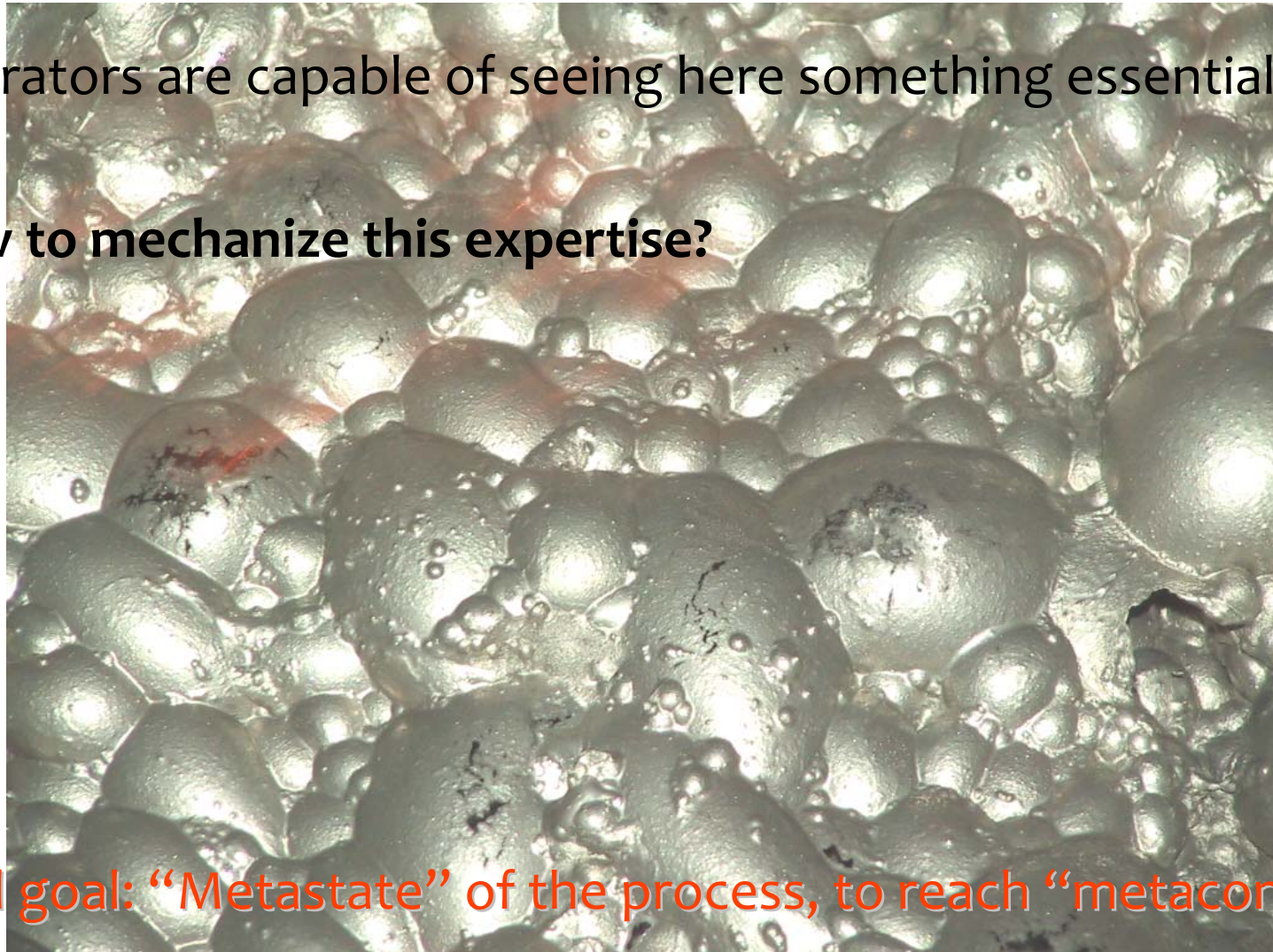




# Need of pattern recognition

- Operators are capable of seeing here something essential...

**How to mechanize this expertise?**



**Overall goal: “Metastate” of the process, to reach “metacontrols”**



# Implementing controls

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- First only necessary controls, simple SISO style – the acute goal is to keep the process up and running
- Later optimizations to enhance, stability, product quality, etc.  
= to maximize profit
- Very much is dependent of the technical and economical constraints: Lesser optimizations are too expensive  
...until technology perhaps offers new possibilities, changing the balances among what is realistic and what is not
- Specially, *information technology* has boosted **availability**
  - Field buses are used for information transfer *from* and *to* the process
  - Computers make it easier to implement new control schemes
  - Automation systems are used for mastering the overall complexity



# Towards stability or instability?

- Automation system becomes less and less stable!
- Reasons for this:
  - Explicit optimization, making the system faster or more “sensitive”
  - Control strategies oscillate, trying to keep track of time-varying processes
- For example, the  $\text{CuSO}_4$  dosage at the Pyhäsalmi plant actively maps the dynamic range, ending in a limit cycle:

Ranking	Condition	Action
1.	IF <i>froth thickness</i> < <i>lower limit</i> <span style="color: red;">Froth collapse situation</span>	—
2.	IF <i>BCR</i> < <i>lower limit</i> OR <i>bubble transparency</i> < <i>lower limit</i> <span style="color: red;">Too “stiff” froth</span>	—
3.	IF <i>zinc content in rougher tailing</i> > <i>upper limit</i> <span style="color: red;">Try to optimize</span>	+
4.	IF <i>zinc content in scavenger tailing</i> > <i>upper limit</i> <span style="color: red;">...</span>	+
5.	IF <i>froth thickness</i> > <i>upper limit</i> <span style="color: red;">Try to condense froth</span>	+
6.	IF <i>BCR</i> OR <i>bubble transparency</i> OR <i>bubble size</i> > <i>upper limit</i> <span style="color: red;">Too “wet” froth</span>	+
7.	ELSE <span style="color: red;">Finally, try to save reagents</span>	—

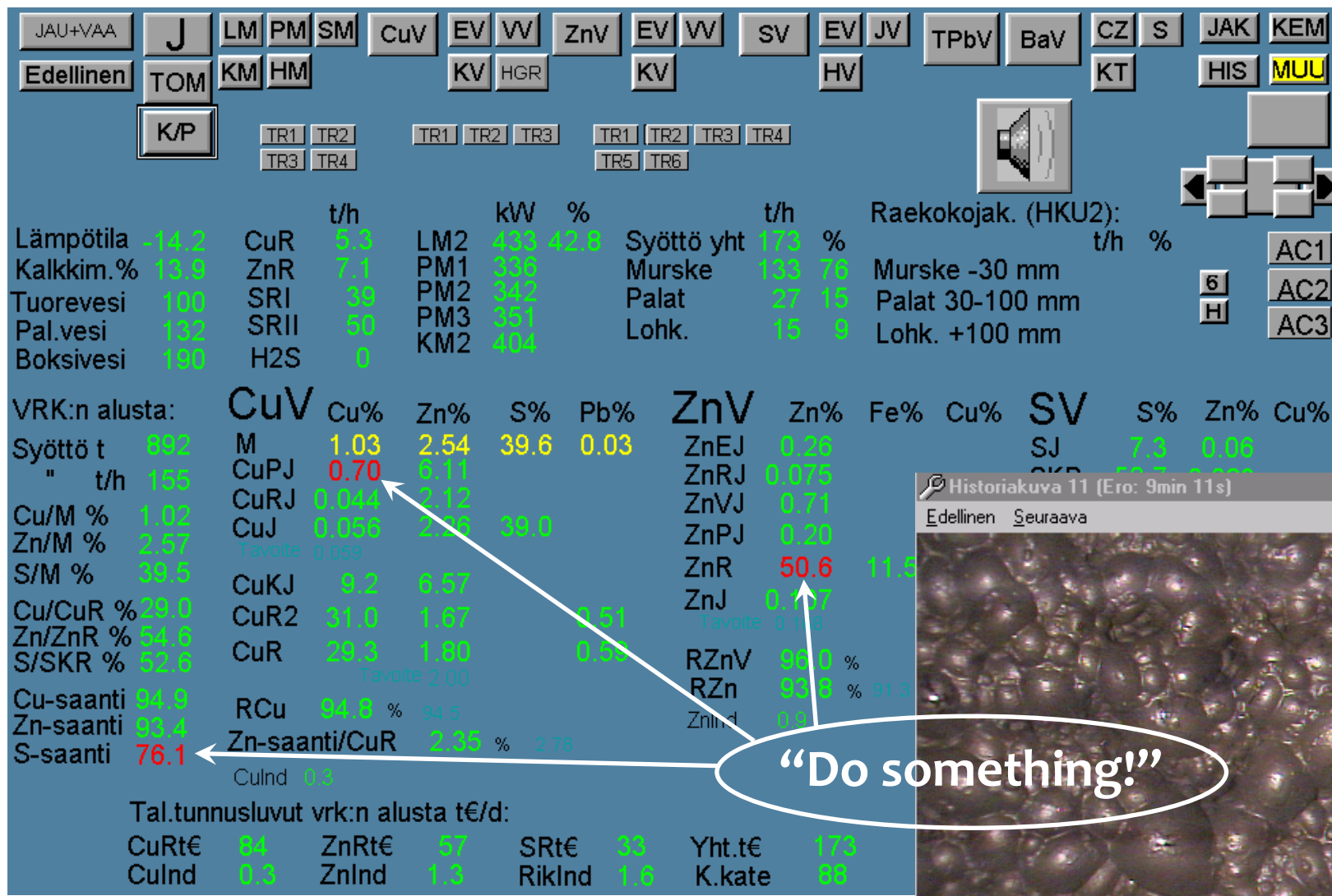




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- Marginally stable cyclic behavior effectively maps the dynamic range of the process
  - This gives the possibility of gaining information of the process –  
“Apply small fluctuations – avoid big catastrophes”!
  - Different parts of a process have characteristic “frequencies” that are determined by the underlying dynamics
  - Complex processes at “evolutionary balance” are characterized by *spectra* of frequencies
  - CLAIM: *Complex systems being coupled need to have compatible spectra* (see Lec. 11)!



# Operators still needed in the loop



“Do something!”



# Some controls in the zinc circuit

- Some inputs

- Ore deposit selection
- Grain sizes
- Air flows
- Acidity (pH)
- Chemicals
  - Copper sulphate (activator)
  - Xanthate (collector)
  - Oil (frother)
- Slurry flow

- Some outputs

- Cell slurry level
- Froth thickness
- X-ray analyses (slow)
  - Zinc contents
  - etc.
- Camera analysis
  - froth speed
  - bubble size
  - bubble load
  - “redness”
  - transparency

- Alarms analyzed separately...

Sensor fusion  
& Control

Not in closed loop

OPERATORS



- 
- Goal 1: Maximize zinc content in the concentrate, minimize it in the waste
  - Goal 2: Robust, reliable production – with no breaks
  - Goal  $n$ : Relieve humans (operators) from the system
  - Cybernetic balance among the needs and possibilities / savings and costs has not yet been reached at the plant
  - There exist too many unknown variables and unknown dependencies among them
  - And even if there existed knowledge, understanding is not deployed: There is no time/instrumentation to implement; finally, it would be **too expensive** – there are balances.



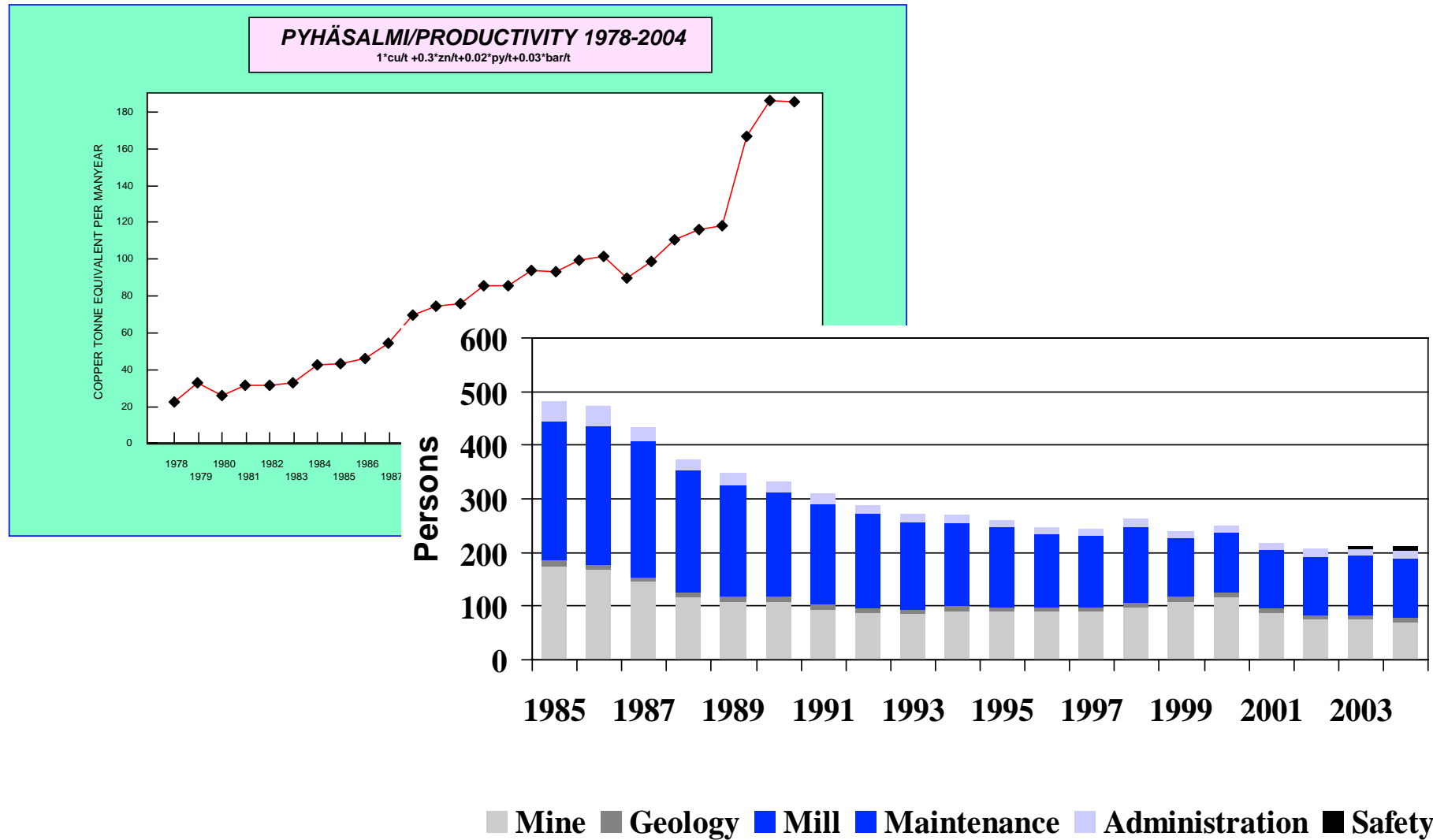
# Humans (operators) in the control loop

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- Changes/disturbances in the process – operators taking action (adjusting controllers, etc.) constitutes a *higher-level controller* above other controls, keeping system in balance
- Why “human controllers” are good:
  - Humans are flexible and multi-purpose actors
  - Humans are self-learning and have “common sense”, deeper understanding
  - Humans are cheap to employ
- Why “human controllers” are *bad*:
  - Humans are inconsistent and unreliable, expertise cannot be transferred
  - Humans are slow (and the delays vary)
  - Humans are expensive in the long run, and need extra facilities
- Loops with humans are necessarily complex – If possible, humans are substituted with mechanized controllers?



# “Evolution” at the plant



# Conclusion

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- The current plants are globally non-optimal – but locally satisfactorily-behaving – and getting ever better controlled
- Technical evolution is always gradual, as there is inertia: operator beliefs and practices also need to adapt
- The directions of development are very much dependent on the agents – research engineers, operators, directors
  - The larger the package of available conceptual/practical toolboxes, the more there exist variables to select from; there are more degrees of freedom = different analysis/design methods, devices and algorithms available
- Also the society of humans (a cybernetic system) needs to be understood to reach smooth production at the plant
- To understand humans in the loops, **the mechanisms of human cognition need to be understood and exploited...**

